Pivotal Estimation Via Self-Normalization for High-Dimensional Linear Models with Errors in Variables

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PIVOTAL ESTIMATION VIA SELF-NORMALIZATION FOR HIGH-DIMENSIONAL LINEAR MODELS WITH ERRORS IN VARIABLES

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We propose a new estimator for the high-dimensional linear regression model with measurement error in the design where the number of coefficients is potentially larger than the sample size. The main novelty of our procedure is that the choice of penalty parameters is pivotal. The estimator is based on applying a self-normalization to the constraints that characterize the estimator. Importantly, we show how to cast the computation of the estimator as the solution of a convex program with second order cone constraints. This allows the use of algorithms with theoretical guarantees and enables reliable implementation. Under sparsity assumptions, we derive $\ell_q$-rates of convergence and show that consistency can be achieved even if the number of regressors exceeds the sample size. We further provide a simple thresholded estimator that yields a provably sparse estimator with similar $\ell_2$ and $\ell_1$-rates of convergence.

1. Introduction. In this paper, we consider the high-dimensional linear model with observation error in the design

$$y_i = x_i^T \beta_0 + \xi_i, \quad z_i = x_i + w_i, \quad i = 1, \ldots, n,$$

where we observe the response variable $y_i$ and the $p$-dimensional vector $z_i$, and do not observe the covariates $x_i$. The scalar errors $\xi_i$ are zero-mean independent random variables and $(y_i, z_i)$ are independent across $i$. The vector $\beta_0 \in \mathbb{R}^p$ is a vector of unknown parameters to be estimated where the dimension $p$ can be much larger than the sample size $n$. We assume that $\beta_0$ is $s$-sparse, that is it has at most $s$ non-zero components. The errors in measurements $w_i$ are assumed to be zero-mean and independent of $\xi_i$. We also assume that the error in measurement covariance matrix $\Gamma = \frac{1}{n} \sum_{i=1}^{n} E(w_i w_i^T)$ is diagonal and admits a data-driven estimator $\hat{\Gamma}$ which is available in several applications as discussed below.

Model (1.1) is motivated by many applications where the covariates may have missing values or are observed with noise. For example, in the field of genomics, the gene expression measurements from microarray data are subject to measurement error. Another example is that of microbiome data where each observation vector


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has a significant proportion of missing components. Many other examples arise in empirical economics and finance, see [17] and [25], and consumer surveys in marketing where random subsets of questions are selected for each consumer to reduce the length of the survey. In these settings a data-driven estimator \( \hat{\Gamma} \) can be constructed based on auxiliary data without measurement errors [24, 8] or even based on \((y_i, z_i)_{i=1}^n\) alone as in the case of missing at random (as one can estimate the frequencies of missing components, see, e.g. [26, 2]). It has been well-documented that ignoring this measurement error leads to biased parameter estimates even in the fixed \( p \) setting, see for example, [17], [13], and [23]. In the high-dimensional framework considered here it is also crucial to account for such measurement errors. In addition to potentially biased estimation, measurement errors can also impact variables selection performance and influence the choice of various penalty parameters, see [29].

High-dimensional linear models with \( p \gg n \) and measurement errors have been studied recently by [1], [4], [9], [10], [11], [19], [20], [22], [25], [26], [27] and [28]. The common thread\(^1\) of these papers is to provide estimators along with the corresponding rates of convergence in different norms. Examples of proposed estimators\(^2\) include the orthogonal matching pursuit as defined in [9], the non-convex \( \ell_1 \)-penalized regression studied in [22] and the conic programming estimator considered in [1]. In particular, under suitable conditions and appropriate choice of penalty parameters, some of these estimators \( \tilde{\beta} \) can attain \( \ell_q \)-rates of convergence of the form

\[
\| \tilde{\beta} - \beta_0 \|_q \leq C(1 + \| \beta_0 \|_2) s^{1/q} \sqrt{\frac{\log p}{n}}, \quad 1 \leq q \leq \infty,
\]

where \( \| \cdot \|_q \) denotes the \( \ell_q \)-norm, and \( C > 0 \) is a constant independent of \( s, p \) and \( n \). It is shown in [1] that these rates are minimax optimal. The rate in (1.2) highlights the impact of the errors in measurements via the \( \ell_2 \)-norm term \( \| \beta_0 \|_2 \), which is not present in the case where covariates are observed without error, and the fact that consistency can be achieved in high-dimensional settings even if \( p \gg n \). However, estimators suggested in the literature rely on suitable choice of penalty parameters based on some specific knowledge of the model (1.1). To construct these estimators, the variance of the unobserved noise \( \xi_i \) and the variance parameters of the measurement noise \( w_i \) should typically be known. For some methods, in addition, one needs to have access to the number \( s \) of non-zero components or to the \( \ell_2 \)-norm of \( \beta_0 \).

In this work, we propose a new estimator of the parameter \( \beta_0 \) in model (1.1) that achieves the optimal rates of convergence in \( \ell_q \)-norm under suitable condi-

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\(^1\)We note that all the cited papers assume independent observations except for [27] that allows for the measurement error for each covariate to be a dependent vector across observations.

\(^2\)These estimators were proposed under various conditions on the design matrix, relations between \( s, p \) and \( n \), and knowledge of some parameters of the problem.
tions. Moreover, a simple thresholded version of the estimator achieves optimal sparsity, while retaining optimal convergence rates. The main novelty of our procedure is the pivotality of the penalty parameters, which makes the estimator particularly appealing for the practical applications. That is, the penalty parameters do not depend on the number of non-zero components, on the $\ell_2$-norm of $\beta_0$, the variance parameter of the errors $\xi_i$, nor on the variance parameters of the errors in the measurements $w_i$. Furthermore, our estimator is a solution of a convex optimization problem.

Notation. Let $J \subseteq \{1, \ldots, p\}$ be a set of integers. We denote by $|J|$ the cardinality of $J$. For a vector $\theta = (\theta_1, \ldots, \theta_p)^T$ in $\mathbb{R}^p$, we denote by $\theta_J$ the vector in $\mathbb{R}^p$ whose $j$-th component satisfies $(\theta_J)_j = \theta_j$ if $j \in J$, and $(\theta_J)_j = 0$ otherwise. We will call $\theta_J$ the restriction of $\theta$ to $J$. We denote the $\ell_2$-norm of a vector $v \in \mathbb{R}^p$ by $\|v\|^2$. The number of non-zero components of a vector $v \in \mathbb{R}^p$ is denoted by $\|v\|_0$. A centered random variable $\xi$ will be called zero-mean subgaussian with variance parameter $\sigma^2$ if $\mathbb{E}[\exp(t\xi)] \leq \exp(t^2\sigma^2/2)$ for all $t \in \mathbb{R}$. A random vector $w \in \mathbb{R}^n$ will be called zero-mean subgaussian with variance parameter $\sigma^2$ if all the random variables of the form $v^T w$ where $\|v\|^2 = 1$ are zero-mean subgaussian with variance parameter $\sigma^2$. For a matrix $A$, we denote by $A_{ij}$ and $A_{ij}$ its $i$-th row and $j$-th column, respectively. We denote by $C, c, C', c'$ positive constants that can be different on different occurencies.

2. Estimator via self-normalization. Here we propose a pivotal estimator that does not require knowledge of typically unknown parameters. Our starting point is the moment condition that characterizes the vector of parameters $\beta_0$ in (1.1)

\begin{equation}
\frac{1}{n} \sum_{i=1}^n \mathbb{E}[z_i(y_i - z_i^T \beta_0) + \Gamma \beta_0] = 0,
\end{equation}

where the term $\Gamma \beta_0$ corrects the bias that arises from using the noisy covariates $z$ instead of the unobserved $x$. The moment condition (2.1) combined with sparsity assumptions on $\beta_0$ motivates the use of penalized methods to cope with high-dimensionality.

We now describe the proposed estimation procedure. Let $$(\hat{\beta}, \hat{t}, \hat{u})$$ be a solution of the constrained minimization problem

\begin{equation}
\min_{\beta \in \mathbb{R}^p, t \in \mathbb{R}^p, u \in \mathbb{R}^p} \|\beta\|_1 + \lambda_t \|t\|_{\infty} + \lambda_u \|u\|_{\infty}:
\end{equation}

\begin{equation}
\frac{1}{n} \sum_{i=1}^n z_i(y_i - z_i^T \beta) + \hat{\Gamma} \beta_j \leq \tau t_j + (1 + \tau) b_j u_j,
\end{equation}

\begin{equation}
\left\{ \frac{1}{n} \sum_{i=1}^n \{z_i(y_i - z_i^T \beta) + \hat{\Gamma} \beta_j\}_j \right\}^{1/2} \leq t_j, \quad |\beta_j| \leq u_j,
\end{equation}

\forall j \leq p.
where \( z_i = (z_{ij})_{j=1}^p \), \( \beta = (\beta_j)_{j=1}^p \), \( u = (u_j)_{j=1}^p \), \( t = (t_j)_{j=1}^p \), and \( \lambda_t \), \( \lambda_u \), \( \tau \) are positive tuning parameters set according to Theorem 1 below. As it is standard in the literature, the statistics \((\hat{\Gamma}_{jj})_{j=1}^p\) are given estimators of the diagonal elements of matrix \( \Gamma \) with \( b_k \) being a bound on its precision satisfying, for any \( n \),

\[
P(\|\hat{\Gamma} - \Gamma\|_\infty > b_k) \leq \epsilon
\]

where \( \epsilon \in (0, 1) \) is a given number. We use \( \hat{\beta} \) as an estimator of \( \beta_0 \) and we call it the self-normalized conic estimator.

The proposed method has a self-normalization feature, which is related to the square-root Lasso [3, 6, 30], the STIV estimator [14] and the self-tuned Dantzig estimator [16]. A key point is the direct use of self-normalization in the moment condition (2.1), cf. the second line of constraints in (2.3), instead of working with one scalar noise level as self-normalization quantity. This idea appeared already in the context of instrumental variable regression, cf. (9.22) in [14], as well as in [15] that deals with linear model with no measurement errors and studies a program close to (2.2) - (2.3) with \( \hat{\Gamma}_{jj} = 0 \), \( u_j = 0 \).

Importantly, (2.2) - (2.3) is a tractable convex optimization problem with linear and second order cone constraints, for which computationally efficient solvers exist. In particular, we used the R package Rmosek for the computation of the estimator.

In some settings, it is of interest to work with estimators that are also sparse. However, the use of many second order constraints makes unlikely that the estimator \( \hat{\beta} \) defined by solving (2.2)-(2.3) is sparse. In such cases, we propose a thresholded version of the self-normalized conic estimator \( \hat{\beta} \). Consider the set of components \( \hat{T} \) defined as

\[
\hat{T} := \left\{ j \in \{1, \ldots, p\} : |\hat{\beta}_j| > \tau \left( \frac{1}{n} \sum_{i=1}^n \{z_{ij}(y_i - \hat{z}_i^T \hat{\beta}) + \hat{\Gamma}_{jj} \hat{\beta}_j\}^2 \right)^{1/2} \right\}
\]

where \( \hat{\beta}_j \) are the components of \( \hat{\beta} \). We define the thresholded self-normalized conic estimator as \( \hat{\beta}_T \) (the restriction of \( \hat{\beta} \) to \( \hat{T} \)).

3. Main results. In this section we state our assumptions and main theoretical results.

3.1. Regularity conditions. In what follows, we consider a setting where \( s \) and \( p \) depend on \( n \), and we state the results in the asymptotics as \( n \) tends to infinity. Condition A below summarizes the assumptions on the data generating process.

**Condition A.** (i) The \( n \times p \) matrix \( X = [x_1; \ldots; x_n]^T \) is deterministic and the vector \( \beta_0 \) satisfies \( \|\beta_0\|_0 \leq s \). (ii) The elements of the random noise vector
\[ \xi = (\xi_i)_{i=1}^n \text{ are independent zero-mean subgaussian random variables with variance parameter } \sigma_{xi}^2 \leq C. \text{ (iii) The measurement error vectors } (w_i)_{i=1}^n \text{ are independent zero-mean subgaussian random vectors with variance parameter } \sigma_w^2 \leq C, \text{ having zero covariances: } E[w_i w_j] = 0 \text{ for all } 1 \leq j < k \leq p, i = 1, \ldots, n. \text{ Moreover, } (w_i)_{i=1}^n \text{ are independent of } \xi = (\xi_i)_{i=1}^n. \]

Condition A(i) assumes a deterministic design and the performance of our estimator depends on the Gram matrix \( \Psi = \frac{1}{n}X^TX \). Like in problems without measurement errors, some characteristics of \( \Psi \) play a key role in the analysis, see \cite{7}. In this paper, we consider \( \ell_q \)-sensitivity characteristics defined for \( q \geq 1 \) as

\[
\kappa_q(s, u) = \min_{J: |J| \leq s} \left( \min_{\Delta \in C_J(u)} \| \Psi \Delta \|_{\infty} \right),
\]

where \( C_J(u) = \{ \Delta \in \mathbb{R}^p : \| \Delta \|_1 \leq u \| \Delta \|_1, u > 0 \text{ and } J \subseteq \{1, \ldots, p\} \}. \) These sensitivity characteristics generalize other well known characteristics such as the restricted eigenvalues of \cite{7}. One can find details on their properties in \cite{14} where the notion of sensitivity characteristic was introduced. Sensitivity characteristics have been used previously in several papers including \cite{14, 16, 25, 26} and \cite{1}. For well-behaved designs that are prevalent in the literature, we have \( \kappa_q(s, u) \geq cs^{-1/q} \) for \( u \geq 1 \) and \( q \in [1, 2] \), where \( c > 0 \) is a constant, see \cite{14}. Conditions A(ii) and A(iii) are standard in the literature on high-dimensional linear regression with errors in measurements, see \cite{1, 22} among others. Moreover, our analysis relies on the quantity \( m_2 := \max_{j=1, \ldots, p} \frac{1}{n} \sum_{i=1}^n x_{ij}^2 \) which is typically uniformly bounded for many designs of interest.

For \( i = 1, \ldots, n \) and \( j = 1, \ldots, p \), we define

\[
U_{ij} = z_{ij}(\xi_i - w_i^T \beta_0) + E[w_{ij}^2] \beta_{0j}
\]

and set \( U_{jk} = \left\{ \frac{1}{n} \sum_{i=1}^n E[|U_{ij}|^k] \right\}^{1/k} \) and \( \Delta_j = |\beta_{0j}| \max_{i=1, \ldots, n} |E[w_{ij}^2]| - \Gamma_{jj} \).

We now state the assumptions on \( U_{jk}, \Delta_j, p \) and \( n \). Let \( \Phi(\cdot) \) denote the standard normal c.d.f.

**Condition B.** (i) The estimator \( \hat{\Gamma} \) is a diagonal matrix and \( b_k \) satisfies \((2.4)\).

For some positive sequence \( \ell_n \) tending to infinity, the following conditions hold:

(ii) \( \max_{1 \leq j \leq p} \{U_{3j}/U_{2j}\} \Phi^{-1}(1 - \alpha/(2pn)) \leq n^{1/6}/\ell_n \), and

(iii) \( \max_{j, \Delta_j > 0} \left\{ n^{-1/6}(\Delta_j/U_{2j}) + n^{-1/2}(U_{3j}/U_{2j})^6 \right\} \Phi^{-1}(1 - \alpha/(2pn)) \leq 1/\ell_n \).

Condition B(i) allows for the use of data-driven estimator of \( \Gamma \). Condition B(ii) is a mild moment condition and allows the application of self-normalized moderate deviation theory, see \cite{12, 18}. In the case of i.i.d. sampling where the covariates \( x_i \) are also drawn from a subgaussian distribution with bounded variance parameter, we have \( E[|U_{ij}|^{3}]^{1/3} \leq C(1 + \| \beta_0 \|_2) \) and \( E[|U_{ij}|^{2}]^{1/2} \geq c \) if \( \xi \) is independent of \( z \).
In fact for many designs we have \( \max_{j \leq p} \{ \mathbb{E}[|U_j|^3]/\mathbb{E}[|U_j|^2] \} \leq C \) so that Condition B(ii) is satisfied provided \( \log^{3/2} p = o(n) \). Condition B(iii) provides a mild sufficient condition to handle the non-i.i.d. case where the terms \( \mathbb{E}[w_{ij}^2] \) change across \( i \) as well. We also view Condition B(iii) a mild moment condition as it is implied by Condition A, B(ii), \( \|\beta_0\|_\infty \leq C \) and \( \max_{j=1,...,p} \|U_j\| \leq C \).

We also introduce a (computable) data-driven quantity

\[
H_n = \max_{j=1,...,p} \left\| \frac{1}{n} \sum_{i=1}^n (z_{ij}z_i^T - \hat{\Gamma}_j) (z_{ij}z_i^T - \hat{\Gamma}_j) \right\|^{1/2}_\infty.
\]

Let \( h_\epsilon \) denote its \((1 - \epsilon)\)-quantile, so that \( \mathbb{P}(H_n > h_\epsilon) \leq \epsilon \). Here and in what follows, we assume that \( \epsilon \in (0, 1) \) is a fixed small number. We will not require the knowledge of \( h_\epsilon \) to implement the method. We will only need that \( h_\epsilon\tau s = o(1) \) as \( n \to \infty \). This is implied by mild moment conditions on \( z_i \)'s and growth conditions on \( p \) and \( s \). For many designs, \( h_\epsilon \) is uniformly bounded as \( \epsilon \to 0 \) and as the sample size grows (see Lemma 3 in the Appendix). Finally, in order to state our theoretical results below, it will be convenient to define for any \( \beta \in \mathbb{R}^p \) the vector \( t(\beta) = (t_j(\beta))_{j=1}^p \) where

\[
t_j(\beta) := \left\{ \frac{1}{n} \sum_{i=1}^n \{z_{ij}(y_i - z_i^T \beta) + \hat{\Gamma}_j \beta \}^2 \right\}^{1/2}, \quad j = 1, \ldots, p.
\]

### 3.2. Properties of self-normalized conic estimator

The following theorem establishes the rates of convergence of the estimator \( \hat{\beta} \).

**Theorem 1.** Let \( 0 < \alpha < 1, 0 < \epsilon < 1 \), and \( 1 \leq q \leq \infty \). Set \( \tau = n^{-1/2} \Phi^{-1}(1 - \alpha/(2p)), \lambda_u = 1/4 \) and \( \lambda_t = 1/(4H_n) \). Assume that

\[
\kappa_q(s, 3)s^{1/q} \geq 8s \{(1 + \tau)h_\epsilon + \tau h_\epsilon + C'(1 + m_2^{1/2})\sqrt{\log(2p^2/\epsilon)/n} \}
\]

where \( C' > 0 \) is a constant that depends only on \( \sigma_w \) and \( \sigma_\xi \). Then, under Conditions A and B, for \( n \) sufficiently large, with probability at least \( 1 - \alpha \{1 + o(1)\} - 2\epsilon - 9\epsilon \) we have

\[
\|\hat{\beta} - \beta_0\|_q \leq \frac{\tau \|t(\beta_0)\|_\infty}{c'\kappa_q(s, 3)} + \frac{(1 + \|\beta_0\|_2)(1 + m_2^{1/2})}{c'\kappa_q(s, 3)} \sqrt{\frac{\log(2p/\epsilon)}{n}} + \frac{b_\epsilon \|\beta_0\|_\infty}{c'\kappa_q(s, 3)},
\]

where the constant \( c' > 0 \) depends only on \( \sigma_w \) and \( \sigma_\xi \).

Theorem 1 provides a bound on the \( \ell_q \)-rate of convergence that depends on the critical quantities of the data generating process. Indeed, it is characterized via \( \kappa_q, m_2, \|t(\beta_0)\|_\infty, \|\beta_0\|_2, \|\beta_0\|_\infty \) and \( b_\epsilon \) which summarizes how good the estimate
The impact of using an estimate $\hat{\Gamma}$ of $\Gamma$ has a factor of $\|\beta_0\|_\infty$ instead of $\|\beta_0\|_2$.

The next corollary specifies the result of Theorem 1 for the standard configuration of the problem usually considered in the literature. It is described by the following conditions: $b_i \leq C \sqrt{\log(2p/\varepsilon)/n}$, $m_2 \leq C$, $\|t(\beta_0)\|_\infty \leq C(1 + \|\beta_0\|_2)$ and $\kappa_q(s, 3) \geq cs^{-1/q}$ for $q \in [1, 2]$ with high probability. Define $\Omega_X := \{X : \kappa_q(s, 3) \geq cs^{-1/q}, \max_{1 \leq j \leq p} \frac{1}{n} \sum_{i=1}^n x_{ij}^4 \leq C\}$. We have the following result.

**Corollary 1.** Assume that the probability that the design matrix $X$ belongs to $\Omega_X$ tends to 1 as $n \to \infty$, and that $b_i \leq C \sqrt{\log(2p/\varepsilon)/n}$. Set $\varepsilon = \epsilon$. Then, under the assumptions of Theorem 1, for $n$ sufficiently large, with probability at least $1 - \alpha - 11\varepsilon - o(1)$ we have

$$
\|\hat{\beta} - \beta_0\|_q \leq C(1 + \|\beta_0\|_2)s^{1/q} \sqrt{\frac{\log(c'p/(\alpha\varepsilon))}{n}}
$$

where $C > 0, c' \geq 1$ are constants.

Note that Corollary 1 exhibits the minimax rate of convergence discussed in (1.2). A major point is that the estimator $\hat{\beta}$ achieves the minimax rate without needing to know $\|\beta_0\|_2, \sigma_{\xi}, \sigma_{w}$ or $s$ (or invoking cross-validation) as required for the procedures previously suggested in the literature. Note that cross-validation in the problem that we consider here remains unjustified theoretically.

**Remark 1.** If the condition on $\kappa_q(s, 3)$ required in Corollary 1 is not satisfied, following the same argument as in [1], we can derive a rate of convergence that depends on $\|\beta_0\|_1$ instead of $\|\beta_0\|_2$, namely

$$
\|\hat{\beta} - \beta_0\|_q \leq C(1 + \|\beta_0\|_1) \sqrt{\frac{\log(c'p)}{n}} \left(1 + \frac{b_i}{\kappa_q(s, 3)}\right).
$$

Next, we consider the data-driven thresholded estimator $\hat{\beta}_{T}$ based on $\hat{T}$ defined in (2.5), and we show that it achieves the sparsity $O(s)$, while preserving the optimal $\ell_1$ and $\ell_2$ rates of convergence.

**Theorem 2.** Let $q \in \{1, 2\}$. Suppose that $s^{1/q} \sqrt{\log(2pm/\alpha)/n} = o(1)$. Furthermore, assume that there exist constants $0 < c < C < \infty$ such that, for any $1 \leq j \leq p$,

$$
c(1 + \|\beta_0\|_2)^2 \leq \frac{1}{n} \sum_{i=1}^n E[\{z_{ij}(\xi_i - w_i^T \beta_0) + \Gamma_{jj} \beta_{0j}\}^2] \leq C(1 + \|\beta_0\|_2)^2.
$$

Then, under the assumptions of Corollary 1, for $n$ sufficiently large, with probability at least $1 - \alpha - 11\varepsilon - o(1)$ we have

$$
\|\hat{\beta}_{T}\|_0 \leq Cs \quad \text{and} \quad \|\hat{\beta}_{T} - \beta_0\|_q \leq C(1 + \|\beta_0\|_2)s^{1/q} \sqrt{\frac{\log(c'p/\alpha)}{n}}
$$
where $C > 0, c' \geq 1$ are constants.

Theorem 2 shows that the estimator $\hat{\beta}_T$ inherits the $\ell_1$ and $\ell_2$ rates of convergence of $\hat{\beta}$ and is also sparse. Estimators with this additional sparsity property have been useful in many settings, see for example [2].

4. Numerical Experiments. In this section, we investigate the performance of the self-normalized conic estimator. In the Supplementary Material we present more detailed simulation results for different designs, which include covariates missing at random, and the thresholded version of the estimator.

We consider the data generating process (1.1) where $\xi_i, w_i, x_i$ are drawn independently satisfying $\xi_i \sim \mathcal{N}(0, \sigma_\xi^2), w_i \sim \mathcal{N}(0, \sigma_w^2 I_{p \times p}), x_i \sim \mathcal{N}(0, \Sigma)$. Here, $I_{p \times p}$ is the identity matrix and $\Sigma$ is $p \times p$ matrix with elements $\Sigma_{ij} = \rho^{|i-j|}$. We set $\sigma_\xi = 1, \sigma_w = 1$ and $\rho = 0.5$. For simplicity, we assume $\sigma_w$ to be known in all calculations, which means that we set $\Gamma = \sigma_w^2 I_{p \times p}$ and $b_\epsilon = 0$. The coefficients of the model are set to $\beta_0 = (1, 1, 1, 1, 0, \ldots, 0)^T$. All results are based on 100 replications.

We compare the performance of the proposed self-normalized estimator (SN-conic) with the performance of the conic estimator (Conic) of [1], the (biased) Lasso estimator of $y$ on $z$, and the no measurement error Lasso estimator with $y$ on the unobserved $x$. For numerical comparison, we report the bias, the average accuracy in $\ell_2$, and the prediction risk $\|X(\hat{\beta} - \beta_0)\|_2/\sqrt{n}$ for each estimator. The Conic estimator is tuned assuming that $\sigma_\xi = 1$ is known ($\tau = \sigma_\xi \sqrt{\log(p/\epsilon)/n}$) while the SN-conic has its penalty parameter set to $\tau = \frac{1}{2} n^{-1/2} \Phi^{-1}(1 - \alpha/(2p))$, $\alpha = 0.05, \lambda_l = 1$ and $\lambda_u = 0.25$. Computations are performed in R and use the optimization software Mosek, an interior point methods solver, wrapped through the R package Rmosek. All estimates are truncated at $10^{-7}$.

The SN-conic estimator provides good results at all three levels of $p$ considered in the simulations, with the performance deteriorating slightly with increase in $p$. Results, reported in Table 1, support our theoretical results regarding consistency of the proposed estimator. We also observe that SN-conic estimator outperforms the Conic estimator in most of the designs considered. This is attractive as the latter was tuned based on knowing $\sigma_w$ and $\sigma_\xi$ whereas the SN-conic estimator does not need the knowledge of these parameters. Another, more obvious observation is the poor performance of (biased) Lasso method that disregards the presence of the measurement error.

Additional simulations are provided in the Supplementary Material, including the case of covariates missing at random. The Supplementary Material also presents results for the proposed thresholded estimator, different choices of parameter, and other estimators in the literature.
Pivotal Estimation for Error in Variables

\[
\begin{array}{lcccccc}
\text{Method} & \text{p} & \text{Bias} & \ell_2\text{-loss} & \text{PR} & \text{Bias} & \ell_2\text{-loss} & \text{PR} \\
\hline
\text{SN-Conic} & 10 & 0.367 & 0.875 & 0.706 & 0.247 & 0.716 & 0.581 \\
 & 100 & 0.628 & 0.891 & 0.919 & 0.536 & 0.822 & 0.818 \\
 & 400 & 0.809 & 1.064 & 1.144 & 0.667 & 0.878 & 0.952 \\
\text{Conic} & 10 & 0.693 & 1.000 & 0.992 & 0.572 & 0.823 & 0.836 \\
 & 100 & 0.749 & 1.030 & 1.785 & 0.655 & 0.942 & 0.971 \\
 & 400 & 0.809 & 1.064 & 1.144 & 0.667 & 0.878 & 0.952 \\
\text{Lasso (Biased)} & 10 & 0.900 & 0.937 & 1.276 & 0.883 & 0.913 & 1.238 \\
 & 100 & 0.941 & 1.003 & 1.322 & 0.909 & 0.969 & 1.277 \\
 & 400 & 0.992 & 1.103 & 1.356 & 0.952 & 1.014 & 1.306 \\
\text{Lasso (No Meas Error)} & 10 & 0.900 & 0.937 & 1.276 & 0.883 & 0.913 & 1.238 \\
 & 100 & 0.941 & 1.003 & 1.322 & 0.909 & 0.969 & 1.277 \\
 & 400 & 0.992 & 1.103 & 1.356 & 0.952 & 1.014 & 1.306 \\
\end{array}
\]

\[n = 200\] \hspace{1cm} \[n = 250\]

\[
\begin{array}{lcccccc}
\text{Method} & \text{p} & \text{Bias} & \ell_2\text{-loss} & \text{PR} & \text{Bias} & \ell_2\text{-loss} & \text{PR} \\
\hline
\text{SN-Conic} & 10 & 0.311 & 0.370 & 0.445 & 0.281 & 0.332 & 0.399 \\
 & 100 & 0.340 & 0.389 & 0.482 & 0.304 & 0.356 & 0.436 \\
\end{array}
\]

\[n = 300\]

\[
\begin{array}{lcccccc}
\text{Method} & \text{p} & \text{Bias} & \ell_2\text{-loss} & \text{PR} \\
\hline
\text{SN-Conic} & 10 & 0.216 & 0.717 & 0.572 \\
 & 100 & 0.496 & 0.716 & 0.734 \\
 & 400 & 0.588 & 0.782 & 0.849 \\
\text{Conic} & 10 & 0.524 & 0.779 & 0.787 \\
 & 100 & 0.603 & 0.808 & 0.878 \\
 & 400 & 0.644 & 0.856 & 0.927 \\
\text{Lasso (Biased)} & 10 & 0.860 & 0.890 & 1.216 \\
 & 100 & 0.954 & 1.274 \\
 & 400 & 0.929 & 1.004 & 1.282 \\
\text{Lasso (No Meas Error)} & 10 & 0.199 & 0.262 & 0.304 \\
 & 100 & 0.267 & 0.307 & 0.375 \\
 & 400 & 0.284 & 0.327 & 0.406 \\
\end{array}
\]

\[n = 300\]

Table 1

For each estimator we report the bias, average \(\ell_2\)-loss (average of \(\|\hat{\beta} - \beta\|_2\) over replications) and the average prediction risk (PR) given by \(\|X(\hat{\beta} - \beta)\|_2/\sqrt{n}\).

Appendix A: Main Proofs

We set \(T = \text{supp}(\beta_0)\) with \(|T| \leq s\). We begin by stating a technical lemma.

**Lemma 1.** For \(a \geq 1\) and \(\gamma > 0\), we have

\[
1 - \Phi(a/(1 + \gamma)) \leq \{1 - \Phi(a)\} \exp(2a^2\gamma).
\]

The next lemma deals with \((\hat{\beta}, \hat{t}, \hat{u})\) defined as the solution to (2.2)-(2.3).

**Lemma 2.** Under Conditions A and B, for \(\tau = n^{-1/2}\Phi^{-1}(1 - \alpha/(2p))\), we have that \(\beta_0\) is feasible in the pivotal conic programming (2.2) with probability at least \(1 - \alpha\{1 + o(1)\} - \epsilon\) for \(n\) sufficiently large. On that event, we have

\[
\|\hat{t}\|_\infty - \|t(\beta_0)\|_\infty \leq \frac{1}{\lambda_t} \|\hat{\beta} - \beta_0\|_1, \quad \text{and}
\]

\[
\text{APPENDIX A: MAIN PROOFS}
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\[
\|\hat{t}\|_\infty - \|t(\beta_0)\|_\infty \leq \frac{1}{\lambda_t} \|\hat{\beta} - \beta_0\|_1, \quad \text{and}
\]
that the triplet \((\beta, z_n, U)\) together with Condition B that implies 
\[
\max_n \bigg\{ \frac{1}{\lambda_u} \| \dot{\beta} - \beta_0 \|_1 + \frac{\lambda_t}{\lambda_u} H_n \| \dot{\beta} - \beta_0 \|_1 \bigg\}.
\]

In addition, using \(\lambda_u = 1/4\) and \(\lambda_t = 1/(4H_n)\), we have \(\dot{\beta} - \beta_0 \in C_T(3)\).

**Proof of Lemma 2.** Let \(\Gamma_{i,j} = E[w_i^2], \Gamma_{i,j} = \frac{1}{n} \sum_{i=1}^n E[w_i^2], \) and \(|\beta_0| = (|\beta_0|)_{j=1}^p\). Recall that we defined \(t_j(\beta) = \left\{ \frac{1}{n} \sum_{i=1}^n (z_{ij}(y_i - z_i T \beta) + \hat{\Gamma}_{ij} \beta_j) \right\}^{1/2}\) and \(U_{ij} = z_{ij}(y_i - z_i T \beta) + \Gamma_{i,j} \beta_{ij}\). For \(j = 1, \ldots, p, i = 1, \ldots, n\), we set \(U_{ij} = z_{ij}(y_i - z_i T \beta) + \Gamma_{i,j} \beta_{ij}\) (note that the optimization problem has \(\hat{\Gamma}_{jj}\) instead of \(\Gamma_{i,j}\)). Remark also that by definition \(\sum_{i=1}^n U_{ij} = \sum_{i=1}^n \hat{\Gamma}_{jj}\). We now show that the triplet \((\beta, t(\beta), |\beta_0|)\) is feasible with high probability. Indeed, the probability that the triplet \((\beta, t(\beta), |\beta_0|)\) violates any constraint satisfies

\[
P \left( \exists j : \frac{1}{n} \sum_{i=1}^n z_{ij}(y_i - z_i T \beta) + \hat{\Gamma}_{jj} \beta_{ij} > \tau t_j(\beta_0) + (1 + \tau) b_\epsilon |\beta_0| \right) = P \left( \exists j : \frac{1}{n} \sum_{i=1}^n U_{ij} + (\hat{\Gamma}_{jj} - \Gamma_{jj}) \beta_{ij} > \tau \left| \frac{\bar{U}_{jj}}{\sqrt{n}} \right|_2 + \tau |(\hat{\Gamma}_{jj} - \Gamma_{jj}) \beta_{ij} | + (1 + \tau) b_\epsilon |\beta_0| \right)
\]

\[
\leq P \left( \exists j : \frac{1}{n} \sum_{i=1}^n U_{ij} > \left| \frac{\bar{U}_{jj}}{\sqrt{n}} \right|_2 + \epsilon \right)
\]

\[
\leq P \left( \exists j : \frac{1}{n} \sum_{i=1}^n U_{ij} \right) + \left( 1 + n^{-1/3} \right) \left\| \bar{U}_{jj} \right\|_2 \leq \left\| \bar{U}_{jj} \right\|_2 + \epsilon,
\]

where we used that \(\| \bar{U}_{jj}/\sqrt{n} \|_2 - t_j(\beta_0) \leq |\hat{\Gamma}_{jj} - \Gamma_{jj}| |\beta_0| \) by definition and \(\max_{j=1, \ldots, p} \| \hat{\Gamma}_{jj} - \Gamma_{jj} \|_2 \leq b_\epsilon\) with probability \(1 - \epsilon\) from Condition B.

We now bound each term in the last display separately. By Condition A, note that \(U_{ij}\) is a zero-mean random variable. Therefore, using Lemma 7.4 in [12] together with Condition B that implies

\[
\sqrt{n}\tau \max_{1 \leq j \leq p} \left\{ \left( \frac{1}{n} \sum_{i=1}^n E[|U_{ij}|^3] \right)^{1/3} \left( \frac{1}{n} \sum_{i=1}^n E[|U_{ij}|^2] \right)^{1/2} \right\} \leq n^{1/6}/\ell_n,
\]

where \(\ell_n \to \infty\), we have

\[
P \left( \frac{1}{n} \sum_{i=1}^n U_{ij} > \frac{\sqrt{n}\tau}{\left( 1 + n^{-1/3} \right)} \left\| \bar{U}_{jj} \right\|_2 \right) \leq \left( 1 - \Phi(\sqrt{n}\tau/(1 + n^{-1/3})) \right) \left( 1 + \frac{A}{\ell_n} \right)
\]

\[
\leq \left( 1 - \Phi(\sqrt{n}\tau) \right) \left( 2n^{-1/3} \left\{ \left( 1 - \frac{a}{2n} \right)^2 \right\} \left( 1 + \frac{A}{\ell_n} \right) \right)
\]

\[
\leq \left( 1 - \Phi(\sqrt{n}\tau) \right) \left( 2n^{-1/3} \left\{ \left( 1 - \frac{a}{2n} \right)^2 \right\} \left( 1 + \frac{A}{\ell_n} \right) \right),
\]

for some universal constant \(A > 0\). Here, we have used Lemma 1, and again Condition B that implies \(n^{-1/3} \left\{ \left( 1 - \frac{a}{2n} \right)^2 \right\} \leq 1/\ell_n^2\).
To bound the last term, set $\Sigma^2_j := \frac{1}{n} \sum_{i=1}^{n} (\Gamma_{i,j} - \Gamma_{jj})^2$, $j = 1, \ldots, p$. Note that
\[
P \left( \exists j : (1 + n^{-1/3}) \left\| \frac{U_{ij}}{\sqrt{n}} \right\|_2 \leq \left\| \frac{U_j}{\sqrt{n}} \right\|_2 \right)
\]
is smaller than
\[
P \left( \exists j : n^{-1/3} \left\| \frac{U_{ij}}{\sqrt{n}} \right\|_2^2 + (1 + n^{-1/3})^2 \Sigma_j^2 \beta_{0j} + \frac{2(1 + n^{-1/3})^2 \beta_{0j}}{n} \sum_{i=1}^{n} U_{ij} (\Gamma_{jj} - \Gamma_{jj}) < 0 \right).
\]
Since $0 \leq \Gamma_{i,j} \leq C$ by Condition A, we deduce that $\{U_{ij}(\Gamma_{i,j} - \Gamma_{jj}) : i = 1, \ldots, n\}$ satisfies the moderate deviation condition for self-normalized sums since $\{U_{ij} : i = 1, \ldots, n\}$ satisfies it by Condition B. Therefore we get
\[
P \left( \exists j : \left\| \frac{1}{n} \sum_{i=1}^{n} U_{ij} (\Gamma_{i,j} - \Gamma_{jj}) \right\| > \frac{\Phi^{-1}(1 - \alpha/(2pn))}{n^{1/2}} \left\{ \frac{1}{n} \sum_{i=1}^{n} U_{ij}^2 (\Gamma_{i,j} - \Gamma_{jj})^2 \right\}^{1/2} \right)
\]
\[
\leq \frac{\alpha}{n} (1 + A/\ell_n^3).
\]
Note that if $\left\{ \frac{1}{n} \sum_{i=1}^{n} U_{ij}^2 (\Gamma_{i,j} - \Gamma_{jj})^2 \right\}^{1/2} = 0$ the result is trivial. Furthermore we have
\[
\left\{ \frac{1}{n} \sum_{i=1}^{n} U_{ij}^2 (\Gamma_{i,j} - \Gamma_{jj})^2 \right\}^{1/2} \leq \left\{ \frac{1}{n} \sum_{i=1}^{n} |U_{ij}|^2 \right\}^{1/2} \max_{1 \leq i \leq n} |\Gamma_{i,j} - \Gamma_{jj}|
\]
and by Condition B, for all $j$ such that $\Delta_j := |\beta_{0j}| \max_{1 \leq i \leq n} |\Gamma_{i,j} - \Gamma_{jj}| > 0$,
\[
\Delta_j \Phi^{-1}(1 - \alpha/(2pn)) \leq \frac{n^{1/6}}{\ell_n} \left\{ \frac{1}{n} \sum_{i=1}^{n} \text{E}[U_{ij}^2] \right\}^{1/2}.
\]
Hence,
\[
P \left( \exists j : (1 + n^{-1/3}) \left\| \frac{U_{ij}}{\sqrt{n}} \right\|_2 \leq \left\| \frac{U_j}{\sqrt{n}} \right\|_2 \right)
\]
(A.2)
\[
\leq P \left( \exists j : n^{-1/3} \left\| \frac{U_{ij}}{\sqrt{n}} \right\|_2^2 < 2(1 + n^{-1/3}) \Phi^{-1}(1 - \alpha/(2pn)) \left\| \frac{U_j}{\sqrt{n}} \right\|_2 \Delta_j \right) + \frac{\alpha}{n} \{1 + A/\ell_n^3\}.
\]
To bound the first term of the RHS of (A.2), set $A_n = \frac{1}{n} \sum_{i=1}^{n} \text{E}[U_{ij}^2 1\{|U_{ij}| \leq M_n\}]$ for some threshold $M_n > 0$. We have, for $t > 0$,
\[
P(\sum_{i=1}^{n} U_{ij}^2 < A_n n - tn) \leq P(\sum_{i=1}^{n} U_{ij}^2 1\{|U_{ij}| \leq M_n\} < A_n n - tn) \leq \exp(-2t^2 n/M_n^4)
by Hoeffding’s inequality. Moreover,
\[
\frac{1}{n} \sum_{i=1}^{n} E[U_{ij}^2] - A_n \leq \frac{1}{n} \sum_{i=1}^{n} E[U_{ij}^2 1\{|U_{ij}| > M_n\}] \leq \frac{1}{n} \sum_{i=1}^{n} E[|U_{ij}|^3]/M_n.
\]
Setting \(M_n = \frac{2}{n} \sum_{i=1}^{n} E[|U_{ij}|^3]/\frac{1}{n} \sum_{i=1}^{n} E[U_{ij}^2]\), we have \(A_n \geq \frac{1}{2n} \sum_{i=1}^{n} E[U_{ij}^2]\).
Then, taking \(t = A_n/2\), and using Condition B(iii) since \(\{P((A_3) P_\beta \text{ and the inequality on } H\text{ by Hoeffding's inequality. Moreover,}\]
\[
\text{12}
\]
\[
\|t(\beta)|_\infty \leq \|\hat{t}\|_\infty \text{ and } \|\hat{\beta}\|_\infty \leq \|\hat{u}\|_\infty \text{ from the definition of the estimator, we have that}\]
\[
\|\|t(\hat{\beta})\|_\infty - \|t(\beta_0)\|_\infty \leq \left\{\frac{1}{n} \sum_{i=1}^{n} (a_i - b_i)^2\right\}^{1/2} \leq \left\{\frac{1}{n} \sum_{i=1}^{n} (\alpha_i - \beta_0)^2\right\}^{1/2}.
\]
Next, since \(\left\{\frac{1}{n} \sum_{i=1}^{n} a_i^2\right\}^{1/2} - \left\{\frac{1}{n} \sum_{i=1}^{n} b_i^2\right\}^{1/2} \leq \left\{\frac{1}{n} \sum_{i=1}^{n} (a_i - b_i)^2\right\}^{1/2}\), we have
\[
|t_j(\beta_0) - t_j(\hat{\beta}|_\infty \leq \frac{1}{n} \sum_{i=1}^{n} \{ (z_{ij}z_i^T - \hat{\mu}_j)(\hat{\beta} - \beta_0)\}^2 = (\hat{\beta} - \beta_0)^T \frac{1}{n} \sum_{i=1}^{n} (z_{ij}z_i^T - \hat{\mu}_j) (z_{ij}z_i^T - \hat{\mu}_j)^T (\hat{\beta} - \beta_0).\]
Thus for \(H_n = \max_{j=1,...,p} \|z_{ij}z_i^T - \hat{\mu}_j\|_{\infty}^2\), we obtain
\[
|t(\beta_0) - t(\hat{\beta}|_\infty \leq H_n \|\hat{\beta} - \beta_0\|_1
\]
and the inequality on \(\|\hat{u}\|_\infty\) stated in the lemma follows.
We now establish the last claim of the lemma. From (A.4), and the inequalities $||t(\hat{\beta})||_\infty \leq ||\hat{t}||_\infty$, $||\hat{\beta}||_\infty \leq ||\hat{t}||_\infty$ we get

\[ ||\hat{\beta}||_1 \leq ||\beta_0||_1 + \lambda_t \{ ||t(\beta_0)||_\infty - ||t(\hat{\beta})||_\infty \} + \lambda_u \{ ||\beta_0||_\infty - ||\hat{\beta}||_\infty \} \leq ||\beta_0||_1 + \lambda_t ||t(\beta_0) - t(\hat{\beta})||_\infty + \lambda_u ||\hat{\beta} - \beta_0||_1. \]

Setting $\lambda_t = \frac{1}{4T_n}$, $\lambda_u = 1/4$, and using the fact that $||\hat{\beta}||_1 = ||\hat{\beta}_T||_1 + ||\hat{\beta}_T^c||_1$, we obtain $\frac{1}{2}||\hat{\beta}_T^c||_1 \leq \frac{3}{2}||\beta_0 - \hat{\beta}_T||_1$. \( \square \)

**Proof of Theorem 1.** Set $Z = [z_1; \ldots; z_n]^T$ and $W = [w_1; \ldots; w_n]^T$. By the triangle inequality,

\[
\left( \frac{1}{n} X^T (\hat{\beta} - \beta_0) \right)_\infty \leq \left( \frac{1}{n} X^T (Y - Z \hat{\beta}) + \hat{\Gamma} \hat{\beta} \right)_\infty + \left( \frac{1}{n} Z^T W - \Gamma \right) \hat{\beta} \right)_\infty + \left( \hat{\Gamma} - \Gamma \right) \hat{\beta} \right)_\infty + \frac{1}{n} Z^T \xi + \left( \frac{1}{n} W^T (\hat{\beta} - \beta_0) \right)_\infty.
\]

We now bound separately the terms on the RHS in (A.6).

As shown at the end of this proof, the second term in (A.6) is bounded with probability at least 1 − 6\( \epsilon \) as follows:

\[
\left( \frac{1}{n} Z^T W - \Gamma \right) \hat{\beta} \right)_\infty \leq \{ \delta_1(\epsilon) + \delta_4(\epsilon) + \delta_5(\epsilon) \} ||\hat{\beta} - \beta_0||_1 + \{ \delta_4'(\epsilon) + \delta_4'(\epsilon) \} ||\beta_0||_2 + \delta(\epsilon) ||\beta_0||_2,
\]

where the quantities $\delta_i(\epsilon)$ are defined in Appendix B.1. By Condition B, the third term in (A.6) is bounded with probability at least 1 − \( \epsilon \) as follows:

\[
||\hat{\Gamma} - \Gamma||_\infty \leq ||(\hat{\Gamma} - \Gamma) \beta_0||_\infty + ||(\hat{\Gamma} - \Gamma) (\hat{\beta} - \beta_0)||_\infty \leq b_4 ||\beta_0||_\infty + b_4 ||\hat{\beta} - \beta_0||_\infty.
\]

Lemma 4 provides, with probability at least 1 − 2\( \epsilon \), the following bound on the fourth term in (A.6):

\[
||\frac{1}{n} Z^T \xi||_\infty \leq ||\frac{1}{n} X^T \xi||_\infty + ||\frac{1}{n} W^T \xi||_\infty \leq \delta_2(\epsilon) + \delta_3(\epsilon).
\]

Finally the last term in (A.6) is bounded, with probability at least 1 − \( \epsilon \), again via Lemma 4:

\[
||\frac{1}{n} W^T (\hat{\beta} - \beta_0) ||_\infty \leq ||\frac{1}{n} X^T W ||_\infty ||\hat{\beta} - \beta_0||_1 \leq \delta_1(\epsilon) ||\hat{\beta} - \beta_0||_1.
\]

Therefore, with probability at least 1 − 9\( \epsilon \) − \( \epsilon \) we have

\[
\left( \frac{1}{n} X^T (\hat{\beta} - \beta_0) \right)_\infty \leq \left( \frac{1}{n} Z^T (Y - Z \hat{\beta}) + \hat{\Gamma} \hat{\beta} \right)_\infty + \tau_0 + \tau_\infty ||\beta_0||_\infty + \tau_2 ||\beta_0||_2 + \tau_1 ||\hat{\beta} - \beta_0||_1,
\]

\( \text{imsart-aos ver. 2014/07/30 file: EIV-Pivotal_Submitted.tex date: October 11, 2017} \)
where

\[
\begin{align*}
\tau_0 & := \delta_2(\varepsilon) + \delta_3(\varepsilon) \leq \{\sigma_\xi m_2^{1/2} + C_{\xi w}\} \sqrt{\frac{2 \log(2p/\varepsilon)}{n}} \\
\tau_\infty & := b_\xi + \delta_5(\varepsilon) \leq b_\xi + C_{\xi w} \sqrt{\frac{2 \log(2p/\varepsilon)}{n}} \\
\tau_2 & := \delta_1'(\varepsilon) + \delta_4'(\varepsilon) \leq \{\sigma_w m_2^{1/2} + C_{\xi w}\} \sqrt{\frac{2 \log(2p/\varepsilon)}{n}} \\
\tau_1 & := 2\delta_1(\varepsilon) + \delta_4(\varepsilon) + \delta_5(\varepsilon) + b_\xi \leq b_\xi + 2\{\sigma_w m_2^{1/2} + C_{\xi w}\} \sqrt{\frac{2 \log(2p^2/\varepsilon)}{n}}.
\end{align*}
\]

Here, \(C_{\xi w}\) is a positive constant depending only on \(\sigma_\xi\) and \(\sigma_w\), and the bounds hold for \(n\) large enough under the condition \(C_{\xi w} \log(p/\varepsilon) = o(n)\).

Next, we bound the first term in \((A.6)\). By the feasibility of \((\hat{\beta}, \hat{t}, \hat{u})\) in \((2.2)\) we have

\[
\left\| \frac{1}{n} X^T (Y - Z\hat{\beta}) + \hat{\Gamma}\hat{\beta} \right\|_\infty \leq \tau \|\hat{t}\|_\infty + (1 + \tau) b_\xi \|\hat{u}\|_\infty.
\]

By Lemma 2 and the choices \(\lambda_\xi = 1/(4H_n)\) and \(\lambda_\mu = 1/4\), with probability \(1 - \alpha(1 + o(1)) - \epsilon\) we have \(\hat{\beta} - \beta_0 \in C_T(3)\) and the bounds on \(\|\hat{t}\|_\infty\) and \(\|\hat{u}\|_\infty\) apply, so that

\[
\left\| \frac{1}{n} X^T (Y - Z\hat{\beta}) + \hat{\Gamma}\hat{\beta} \right\|_\infty \leq \tau \|t(\beta_0)\|_\infty + \tau \frac{1 + \lambda_\mu}{\lambda_\xi} \|\hat{\beta} - \beta_0\|_1 + (1 + \tau) b_\xi \left\{\|\beta_0\|_\infty + 5\tau H_n \|\hat{\beta} - \beta_0\|_1 + (1 + \tau) b_\xi \left\{\|\beta_0\|_\infty + 5\|\hat{\beta} - \beta_0\|_1\right.\right\}.
\]

Next, on the event \(\hat{\beta} - \beta_0 \in C_T(3)\) we bound the LHS of \((A.8)\) from below via the \(\ell_q\)-sensitivity. Plugging that lower bound and \((A.9)\) in \((A.8)\) we find

\[
\kappa_q(s, 3) \|\hat{\beta} - \beta_0\|_q \leq \left\| \frac{1}{n} X^T X (\hat{\beta} - \beta_0) \right\|_\infty
\]

\[
\leq \tau \|t(\beta_0)\|_\infty + \tau_0 + \{(1 + \tau) b_\xi + \tau_\infty\} \|\beta_0\|_\infty + \tau_2 \|\beta_0\|_2 + \hat{\mu}_1 \|\hat{\beta} - \beta_0\|_1,
\]

where \(\hat{\mu}_1 = \tau_1 + 5\tau H_n + 5(1 + \tau) b_\xi\). Note that

\[
\hat{\mu}_1 \leq \tau_1 + 5\tau H_\xi + 5(1 + \tau) b_\xi \leq (1 + \tau) b_\xi + \tau h_\xi + C'(1 + m_n^{1/2}) \sqrt{\log(2p^2/\varepsilon)/n}
\]

with probability \(1 - \epsilon\) where \(C' = \sigma_w \vee C_{w\xi}\) is bounded by a constant since \(\sigma_w \vee \sigma_\xi \leq C\) under Condition A. Moreover, since \(\hat{\beta} - \beta_0 \in C_T(3)\) we have

\[
\|\hat{\beta} - \beta_0\|_1 \leq 4\|(\hat{\beta} - \beta_0)\|_1 \leq 4s^{1-1/q} \|\hat{\beta} - \beta_0\|_q \leq 4s^{1-1/q} \|\hat{\beta} - \beta_0\|_q.
\]

Thus under the condition of the theorem on \(\kappa_q(s, 3)\), we have with probability \(1 - \alpha(1 + o(1)) - 2\epsilon - 9\epsilon\) that

\[
\frac{\kappa_q(s, 3)}{2} \|\hat{\beta} - \beta_0\|_q \leq \tau \|t(\beta_0)\|_\infty + \tau_0 + \{(1 + \tau) b_\xi + \tau_\infty\} \|\beta_0\|_\infty + \tau_2 \|\beta_0\|_2.
\]
The result follows by noticing that \((1 + \tau)b_t \leq 2b_t \leq 2\tau_\infty\) for large enough \(n\).

Proof of (A.7). We have
\[
\| (\frac{1}{n}Z^TW - \Gamma)\hat{\beta} \|_\infty \leq \| (\frac{1}{n}Z^TW - \Gamma)\beta_0 \|_\infty + \| (\frac{1}{n}Z^TW - \Gamma)(\hat{\beta} - \beta_0) \|_\infty
\]
\[
\leq \| (\frac{1}{n}Z^TW - \Gamma)\beta_0 \|_\infty + \| \frac{1}{n}X^TW\beta_0 \|_\infty + \| \frac{1}{n}X^TW\|_\infty \| \hat{\beta} - \beta_0 \|_1
\]
\[
\leq \| (\frac{1}{n}W^TW - \Gamma)\beta_0 \|_\infty + \| \frac{1}{n}X^TW\beta_0 \|_\infty + \| \frac{1}{n}X^TW\|_\infty \| \hat{\beta} - \beta_0 \|_1.
\]

By Lemma 4 we get, with probability at least \(1 - 3\epsilon\),
\[
\| \frac{1}{n}X^TW\|_\infty \leq \delta_1(\epsilon)
\]
\[
\| \frac{1}{n}W^TW - \Gamma \|_\infty \leq \| \frac{1}{n}W^TW - \frac{1}{n}\text{Diag}(W^TW) \|_\infty + \| \frac{1}{n}\text{Diag}(W^TW) - \Gamma \|_\infty
\]
\[
\leq \delta_4(\epsilon) + \delta_5(\epsilon).
\]

Finally, Lemma 5 and Lemma 4 yield that, with probability at least \(1 - 3\epsilon\),
\[
\| \frac{1}{n}X^TW\beta_0 \|_\infty \leq \delta_1(\epsilon)\|\beta_0\|_2
\]
\[
\| (\frac{1}{n}W^TW - \Gamma)\beta_0 \|_\infty \leq \| \frac{1}{n}(W^TW - \text{Diag}(W^TW))\beta_0 \|_\infty
\]
\[
+ \| (\frac{1}{n}\text{Diag}(W^TW) - \Gamma)\beta_0 \|_\infty
\]
\[
\leq \delta_4(\epsilon)\|\beta_0\|_2 + \| \frac{1}{n}\text{Diag}(W^TW) - \Gamma \|_\infty \| \beta_0 \|_\infty
\]
\[
\leq \delta_4(\epsilon)\|\beta_0\|_2 + \delta_5(\epsilon)\|\beta_0\|_\infty.
\]

Proof of Corollary 1. By Theorem 1 with probability \(1 - \alpha \{1 + o(1)\} - 11\epsilon\) we have
\[
\| \hat{\beta} - \beta_0 \|_q \leq \frac{\tau\|t(\beta_0)\|_\infty}{c'\kappa_q(s, 3)} + \frac{(1 + \|\beta_0\|_2)(1 + m_2^{1/2})}{c'\kappa_q(s, 3)} \sqrt{\frac{\log(2p/\epsilon)}{n}} + \frac{b_\epsilon\|\beta_0\|_\infty}{c'\kappa_q(s, 3)}.
\]
Under the additional condition \(X \in \Omega_X\), we have by Lemma 3 that \(P(H_n \leq C) \geq 1 - o(1)\). Therefore we have that with probability \(1 - \alpha \{1 + o(1)\} - 11\epsilon - o(1)\)
\[
\| \hat{\beta} - \beta_0 \|_q \leq C s^{1/q} \left\{ \tau\|t(\beta_0)\|_\infty + (1 + \|\beta_0\|_2) \sqrt{\frac{\log(2p/\epsilon)}{n}} + b_\epsilon\|\beta_0\|_\infty \right\}
\]

since \(m_2^{1/2} \leq \{\max_{j \leq p} \frac{1}{n} \sum_{i=1}^n x_{ij}^4 \}^{1/4} \leq C^{1/4}\) when \(X \in \Omega_X\). Using the triangle
inequality, we obtain

\[
\|t(\beta_0)\|_\infty = \max_{j \leq p} \left\{ \frac{1}{n} \sum_{i=1}^{n} \left\{ z_{ij} (\xi_i - w_i^T \beta_0) + \hat{\Gamma}_{jj} \beta_{0j} \right\}^2 \right\}^{1/2} \\
\leq \max_{j \leq p} \left\{ \frac{1}{n} \sum_{i=1}^{n} \left\{ z_{ij} (\xi_i - w_i^T \beta_0) \right\}^2 \right\}^{1/2} + |\hat{\Gamma}_{jj} \beta_{0j}| \\
\leq (i) \max_{j \leq p} \left\{ \frac{1}{n} \sum_{i=1}^{n} (\xi_i - w_i^T \beta_0)^2 \right\}^{1/2} + |\hat{\Gamma}_{jj} \beta_{0j}| + b_c \|\beta_0\|_\infty \\
\leq (ii) \max_{j \leq p} \left\{ \frac{1}{n} \sum_{i=1}^{n} (\xi_i - w_i^T \beta_0)^2 \right\}^{1/4} \left\{ \frac{1}{n} \sum_{i=1}^{n} (\xi_i - w_i^T \beta_0)^4 \right\}^{1/4} + |\hat{\Gamma}_{jj} \beta_{0j}| + b_c \|\beta_0\|_\infty \\
\leq (iii) \max_{j \leq p} \left\{ \frac{1}{n} \sum_{i=1}^{n} (w_i^T)^4 \right\}^{1/4} \left\{ \frac{1}{n} \sum_{i=1}^{n} (\xi_i - w_i^T \beta_0)^4 \right\}^{1/4} + \max_{j \leq p} \left\{ \frac{1}{n} \sum_{i=1}^{n} (\xi_i - w_i^T \beta_0)^4 \right\}^{1/4} + |\hat{\Gamma}_{jj} \beta_{0j}| + b_c \|\beta_0\|_\infty,
\]

where (i) follows from the inequality \( \|\hat{\Gamma} - \Gamma\|_\infty \leq b_c \) which holds with probability \( 1 - \varepsilon \) by Condition B, (ii) follows from the Cauchy-Schwarz inequality, and (iii) from the triangle inequality. On the event \( X \in \Omega_X \), we have \( \max_{j \leq p} \left\{ \frac{1}{n} \sum_{i=1}^{n} (w_i^T)^4 \right\}^{1/4} \leq C \). Note that \( w_{ij}, i = 1, \ldots, n, j = 1, \ldots, p \), are \( \sigma_w \)-subgaussian random variables with \( \sigma_w \leq C \). Therefore, by Lemmas 6 and 7, \( \max_{i \leq n, j \leq p} \frac{1}{n} \sum_{i=1}^{n} E[w_i^4] \leq C' \), \( E[\max_{i \leq n, j \leq p} |w_{ij}|^4] \leq C'' \log^2(pn) \), and

\[
E \left[ \max_{j \leq p} \frac{1}{n} \sum_{i=1}^{n} w_i^4 - E[w_i^4] \right] \leq C' \frac{\log(p)}{n} \log^2(pn) + C'' \sqrt{\frac{\log(p)}{n} \log^2(pn)} \leq o(1)
\]

where we have used the relation \( \log^3(2p) = o(n) \) following from Condition B(ii). Then using Markov’s inequality and the fact that \( w_i \)'s are subgaussian, with probability \( 1 - o(1) \) we get \( \max_{j \leq p} \left\{ \frac{1}{n} \sum_{i=1}^{n} w_i^4 \right\}^{1/4} \leq C'' \).

Next note that \( \left\{ \frac{1}{n} \sum_{i=1}^{n} (\xi_i - w_i^T \beta_0)^4 \right\}^{1/4} \leq C'(1 + \|\beta_0\|_2) \) with probability \( 1 - o(1) \). Indeed, each of the random variables \( \xi_i := \xi_i - w_i^T \beta_0 \) is subgaussian with parameter bounded by \( C(1 + \|\beta_0\|_2) \). Thus we have

\[
\text{Var} \left( \frac{1}{n} \sum_{i=1}^{n} \xi_i^4 \right) \leq \frac{1}{n^2} \sum_{i=1}^{n} E[\xi_i^8] \leq C'(1 + \|\beta_0\|_2)^8 / n.
\]

Therefore, using Markov’s inequality, we get with probability at least \( 1 - n^{-1/2} \),

\[
\frac{1}{n} \sum_{i=1}^{n} \xi_i^4 \leq \frac{1}{n} \sum_{i=1}^{n} \hat{\xi}_i^4 - \frac{1}{n} \sum_{i=1}^{n} E[\xi_i^4] + C(1 + \|\beta_0\|_2)^4 \leq n^{1/4} C'(1 + \|\beta_0\|_2)^4 / \sqrt{n} + C(1 + \|\beta_0\|_2)^4 \leq C''(1 + \|\beta_0\|_2)^4.
\]
Thus with probability $1 - \varepsilon - o(1)$ we have
\[ \|t(\beta_0)\|_\infty \leq C(1 + \|\beta_0\|_2) + (C + b_\varepsilon)\|\beta_0\|_\infty. \]

Since $\tau = n^{-1/2}\Phi^{-1}(1 - \alpha/(2p)) \leq C\sqrt{\log(2p/\alpha)/n}$, $b_\varepsilon \leq C\sqrt{\log(2p/\varepsilon)/n}$ and $\|\beta_0\|_\infty \leq \|\beta_0\|_2$, the result follows. \qed

**APPENDIX B: AUXILIARY LEMMAS**

**Lemma 3.** Under Conditions A and B, if $\max_{j \leq p} \frac{1}{n} \sum_{i=1}^n x_{ij}^4 \leq C$, we have that $P(H_n \leq C') = 1 - o(1)$.

**Proof of Lemma 3.** We have
\[
H_n^2 = \max_{1 \leq j, k, \ell \leq p} \left| \frac{1}{n} \sum_{i=1}^n (z_{ij} z_{ik} - \hat{\Gamma}_{jk})(z_{ij} z_{i\ell} - \hat{\Gamma}_{j\ell}) \right|
\leq \max_{1 \leq j, k, \ell \leq p} \left| \frac{1}{n} \sum_{i=1}^n z_{ij}^2 z_{ik} z_{i\ell} \right| + \|\hat{\Gamma}\|_\infty^2
+ 2\|\hat{\Gamma}\|_\infty \max_{1 \leq j, k \leq p} \left| \frac{1}{n} \sum_{i=1}^n z_{ij} z_{ik} \right| .
\]

Note that
\[
\left| \frac{1}{n} \sum_{i=1}^n z_{ij}^2 z_{ik} z_{i\ell} \right| \leq \frac{1}{n} \sum_{i=1}^n z_{ij}^2 \frac{z_{ik}^2 + z_{i\ell}^2}{2}
\leq \frac{1}{4} \left| \frac{1}{n} \sum_{i=1}^n z_{ij}^4 + z_{ik}^4 \right| + \frac{1}{4} \left| \frac{1}{n} \sum_{i=1}^n z_{ij}^4 + z_{i\ell}^4 \right|
\leq \max_{j \leq p} \frac{1}{n} \sum_{i=1}^n z_{ij}^4.
\]

Moreover,
\[
\max_{j \leq p} \frac{1}{n} \sum_{i=1}^n z_{ij}^4 \leq 8 \max_{j \leq p} \frac{1}{n} \sum_{i=1}^n x_{ij}^4 + 8 \max_{j \leq p} \frac{1}{n} \sum_{i=1}^n w_{ij}^4 \leq 8C + 8 \max_{j \leq p} \frac{1}{n} \sum_{i=1}^n w_{ij}^4 .
\]

Since $w_{ij}$ are $\sigma_w$-subgaussian random variables with $\sigma_w \leq C$, Lemma 6 yields $M_4 = E[\max_{i \leq n, j \leq p} w_{ij}^4] \leq C \log^2 (pn)$. This and Lemma 7 imply
\[
E[\max_{j \leq p} \frac{1}{n} \sum_{i=1}^n w_{ij}^4] \leq \frac{CM_4 \log(2p)}{n} + \sqrt{\frac{CM_4 \log(2p)}{n}} \max_{j \leq p} \left( \frac{1}{n} \sum_{i=1}^n E[w_{ij}^4] \right)^{1/2}
\leq \frac{C' \log^3 (pn)}{n} + \sqrt{\frac{C' \log^3 (pn)}{n}} = o(1)
\]
where the last equality follows from the relation $\Phi^{-1}(1 - \alpha/(2p)) = o(n^{-1/6})$. The result now follows since $\|\hat{\Gamma}\|_\infty$ is bounded: $\|\hat{\Gamma}\|_\infty \leq b_\varepsilon + \|\Gamma\|_\infty$. \qed

**B.1. Bounds on the stochastic error terms.** The following technical lemmas were proved in [1] and [26] and are stated here for completeness. For a square matrix $A$, we denote by $\text{Diag}\{A\}$ the matrix with the same dimensions as $A$, the same diagonal elements, and all off-diagonal elements equal to zero.
Lemma 4. Let $0 < \varepsilon < 1$ and assume Condition A holds. Then, with probability at least $1 - \varepsilon$ (for each event),

$$\| \frac{1}{n} X^T W \|_\infty \leq \delta_1(\varepsilon), \quad \| \frac{1}{n} X^T \xi \|_\infty \leq \delta_2(\varepsilon), \quad \| \frac{1}{n} W^T \xi \|_\infty \leq \delta_3(\varepsilon),$$

$$\| \frac{1}{n} (W^T W - \text{Diag}(W^T W)) \|_\infty \leq \delta_4(\varepsilon), \quad \| \frac{1}{n} \text{Diag}(W^T W) - \Gamma \|_\infty \leq \delta_5(\varepsilon),$$

where $m_2 := \max_{1 \leq j \leq p} \frac{1}{n} \sum_{i=1}^n X_{ij}^2$,

$$\delta_1(\varepsilon) = \sigma_w \sqrt{\frac{2m_2 \log(2p/\varepsilon)}{n}}, \quad \delta_2(\varepsilon) = \sigma_\xi \sqrt{\frac{2m_2 \log(2p/\varepsilon)}{n}},$$

$$\delta_3(\varepsilon) = \delta_5(\varepsilon) = \varpi(\varepsilon, 2p), \quad \delta_4(\varepsilon) = \varpi(\varepsilon, p(p - 1)),$$

and for an integer $N$, $\varpi(\varepsilon, N) = \max \left( \frac{\gamma_0 \sqrt{2 \log(N/\varepsilon)}}{n}, \frac{2 \log(N/\varepsilon)}{t_0 n} \right)$, where $\gamma_0, t_0$ are positive constants depending only on $\sigma_\xi, \sigma_w$.

Lemma 5. Let $0 < \varepsilon < 1$, $\theta^* \in \mathbb{R}^p$ and assume that Condition A holds. Then, with probability at least $1 - \varepsilon$, $\| \frac{1}{n} X^T W \theta^* \|_\infty \leq \delta_1'(\varepsilon)\|\theta^*\|_2$, where $\delta_1'(\varepsilon) = \sigma_w \sqrt{\frac{2m_2 \log(2p/\varepsilon)}{n}}$. In addition, with probability at least $1 - \varepsilon$,

$$\| \frac{1}{n} (W^T W - \text{Diag}(W^T W)) \theta^* \|_\infty \leq \delta_4'(\varepsilon)\|\theta^*\|_2,$$

where $\delta_4'(\varepsilon) = \max \left( \frac{\gamma_2 \sqrt{2 \log(2p/\varepsilon)}}{n}, \frac{2 \log(2p/\varepsilon)}{t_2 n} \right)$, and $\gamma_2, t_2$ are positive constants depending only on $\sigma_w$.

Lemma 6. (1) If $X$ is a centered subgaussian random variable with parameter $\gamma$, it follows that for any $k > 0$ $\mathbb{E}[|X|^k] \leq k2^{k/2}\gamma^k(k/2)$ and for $p \geq 1$ we have $\{\mathbb{E}[|X|^k]\}^{1/k} \leq C\gamma \sqrt{k}$. (2) If $X_{j, i}, j = 1, \ldots, N$, is a collection of centered subgaussian variables with parameter $\gamma$, then for $k \geq 1$ we have $\mathbb{E} \left[ \max_{j \leq N} |X_j|^k \right] \leq \gamma^k \log^{k/2}(NC_k)$ for some constant $C_k$ that depends only on $k$.

Lemma 7. (e.g., [1]) Let $X_i, i = 1, \ldots, n$, be independent random vectors in $\mathbb{R}^p, p \geq 3$. Define $\bar{m}_k := \max_{j \leq p} \frac{1}{n} \sum_{i=1}^n \mathbb{E}[|X_{ij}|^k]$ and $M_k \geq \mathbb{E}\left[ \max_{1 \leq i \leq n} |X_i|^k \right]$. Then

$$\mathbb{E} \left[ \max_{j \leq p} \frac{1}{n} \sum_{i=1}^n |X_{ij}|^k - \mathbb{E}[|X_{ij}|^k] \right] \leq 2C^2 \frac{\log p}{n} M_k + 2C \sqrt{\frac{\log p}{n} M_k^{1/2} \bar{m}_k^{1/2}}$$

for some universal constant $C$. 
REFERENCES


2012.


B. Supplementary Material: Deferred Proofs.

Proof of Lemma 1. Note that \( \log(1 - \Phi(t)) \) is a concave function so that the supergradient inequality yields

\[
\log\{1 - \Phi(a/(1 + \gamma))\} \leq \log\{1 - \Phi(a)\} + \phi(a) \frac{\gamma}{1 - \Phi(a)} + \gamma a,
\]

where \( \phi \) denotes the Gaussian density function. The result follows by noting that \( \frac{\phi(t)}{1 - \Phi(t)} \leq \{t^2 + 1\}/t \leq 2t \) if \( t \geq 1 \), and exponentiating both sides of the inequality.

\( \Box \)

Proof of Theorem 2. Recall that \( t_j(\beta) = \{\frac{1}{n} \sum_{i=1}^n \{ z_{ij}(y_i - z_i^T \beta) + \hat{\Gamma}_{jj}\beta_j \}^2 \}^{1/2} \) and define \( \tilde{t}_j(\beta) = \{\frac{1}{n} \sum_{i=1}^n \{ z_{ij}(y_i - z_i^T \beta) + \Gamma_{jj}\beta_j \}^2 \}^{1/2} \). Then we can write the threshold in the \( j \)th component of the estimator as \( \tilde{v}_j = \tau t_j(\hat{\beta})/\frac{1}{n} \sum_{i=1}^n z_{ij}^2 \), \( j = 1, \ldots, p \). Further, note that \( E[\tilde{t}_j^2(\beta_0)] = \frac{1}{n} \sum_{i=1}^n E[\{ z_{ij}(\xi_i - w_i^T \beta_0 + \Gamma_{jj}\beta_j) \}^2] \).

We first derive upper and lower bounds on \( t_j(\hat{\beta}) \) by controlling the value

\[
|t_j(\hat{\beta}) - E[\tilde{t}_j^2(\beta_0)]|^{1/2} \leq |t_j(\hat{\beta}) - t_j(\beta_0)| + |t_j(\beta_0) - \tilde{t}_j(\beta_0)| + |\tilde{t}_j(\beta_0) - E[\tilde{t}_j^2(\beta_0)]|^{1/2}
\]

via triangle inequality and using the bracketing

\[
(B.1) \quad c(1 + ||\beta_0||_2)^2 \leq E[\tilde{t}_j^2(\beta_0)] \leq C(1 + ||\beta_0||_2)^2
\]

that holds by assumption.

By (A.5) we have with probability \( 1 - o(1) \)

\[
|t_j(\hat{\beta}) - t_j(\beta_0)| \leq H_n ||\hat{\beta} - \beta_0||_1 \leq C||\beta - \beta_0||_1 = o(1 + ||\beta_0||_2)
\]

since \( H_n \leq C \) with probability \( 1 - o(1) \) by Lemma 3 when \( X \in \Omega_X \), Condition A and B hold, and \( ||\beta - \beta_0||_1 = o(1 + ||\beta_0||_2) \) by Theorem 1 with \( \alpha = \log n \) under the assumed condition \( s^{1/q} \sqrt{\log(2mp/\alpha)/n} = o(1) \) for \( q \in \{1, 2\} \).

Moreover, we have

\[
|t_j(\beta_0) - \tilde{t}_j(\beta_0)| \leq |\hat{\Gamma}_{jj} - \Gamma_{jj}| ||\beta_0||_2 \leq b_\varepsilon ||\beta_0||_2 = o(||\beta_0||_2)
\]

under our conditions that imply \( b_\varepsilon = o(1) \).

Next, Lemma 7 implies

\[
E \left[ \max_{j \leq p} \left| \tilde{t}_j^2(\beta_0) - E[\tilde{t}_j^2(\beta_0)] \right| \right] \leq \frac{CM_2 \log(3p)}{n} + \sqrt{\frac{CM_2 \log(2p)}{n}} \max_{j \leq p} \{ E[\tilde{t}_j^2(\beta_0)] \}^{1/2}
\]
where $M_2 := \mathbb{E}[\max_{i \leq n, j \leq p} |z_{ij} (\xi_i - w_i^T \beta_0) + \Gamma_{jj} \beta_{0j}|^2]$. The quantity $M_2$ satisfies

\begin{align}
M_2 & \leq 2\mathbb{E}[\max_{i \leq n, j \leq p} |x_{ij} (\xi_i - w_i^T \beta_0) + \Gamma_{jj} \beta_{0j}|^2] \\
& + 2\mathbb{E}[\max_{i \leq n, j \leq p} |w_{ij} (\xi_i - w_i^T \beta_0) + \Gamma_{jj} \beta_{0j}|^2] \\
& \leq 4 \max_{i \leq n, j \leq p} |x_{ij}|^2 \mathbb{E}[\max_{i \leq n} |\xi_i - w_i^T \beta_0|^2] + 8|\Gamma_{jj} \beta_{0j}|^2 \\
& + 4\mathbb{E}[\max_{i \leq n, j \leq p} |w_{ij}|^2 \mathbb{E}[\max_{i \leq n} |\xi_i - w_i^T \beta_0|^2] \\
& \leq C \max_{i \leq n, j \leq p} |x_{ij}|^2 (1 + \|\beta_0\|^2_2) \log(n) + C\|\beta_0\|^2_2 \\
& + 4\mathbb{E}[\max_{i \leq n, j \leq p} |w_{ij}|^2 \mathbb{E}[\max_{i \leq n} |\xi_i - w_i^T \beta_0|^2]^{1/2} \\
& \leq C'n^{1/2}(1 + \|\beta_0\|^2_2) \log(n) + C \log(pn)(1 + \|\beta_0\|^2_2) \log(n)
\end{align}

(B.2)

where we used the inequalities $\max_{i \leq n, j \leq p} |x_{ij}| \leq n^{1/4} \max_{i \leq n, j \leq p} \left( \frac{1}{n} \sum_{i=1}^n x_{ij}^4 \right)^{1/4} \leq Cn^{1/4}$ and Lemma 6. Finally, note that

\begin{align}
\max_{j \leq p} |\tilde{t}_j(\beta_0) - \{\mathbb{E}[\tilde{t}_j^2(\beta_0)]\}]^{1/2}| & \leq \max_{j \leq p} \frac{|\tilde{t}_j^2(\beta_0) - \mathbb{E}[\tilde{t}_j^2(\beta_0)]|}{\{\mathbb{E}[\tilde{t}_j^2(\beta_0)]\}]^{1/2} \\
& \leq \max_{j \leq p} \frac{|\tilde{t}_j^2(\beta_0) - \mathbb{E}[\tilde{t}_j^2(\beta_0)]|}{\mathbb{E}[\tilde{t}_j^2(\beta_0)]^{1/2}} \\
& \leq O_P\left( \sqrt{C'n^{1/2} + C \log(pn)} \right) (1 + \|\beta_0\|^2_2) \log(n) \log(pn) \\
& + O_P\left( \sqrt{C'n^{1/2} + C \log(pn)} \right)^{1/2} (1 + \|\beta_0\|^2_2) \log(n) \log(pn)
\end{align}

where we used Markov’s inequality, (B.2) and the fact that $\log^2(n) \log^2(pn) = o(n)$, which is due to the relation $\Phi^{-1}(1 - \alpha/(2pn)) = o(n^{1/6})$ in Condition B(ii).

Thus, uniformly over $j \in \{1, \ldots, p\}$, we have

$$|\tilde{t}_j(\beta) - \{\mathbb{E}[\tilde{t}_j^2(\beta_0)]\}]^{1/2}| = (1 + \|\beta_0\|^2_2) o_P(1).$$

This implies that $|t_j(\beta)|$ satisfies, with high probability, the same bracketing as $|\{\mathbb{E}[\tilde{t}_j^2(\beta_0)]\}]^{1/2}$, cf. (B.1). Since $\frac{1}{n} \sum_{i=1}^n \tilde{z}_{ij}^2$ is bounded away from zero and from above by constants uniformly in $j$ with probability $1 - o(1)$, we have $\min_{j \leq p} \tilde{v}_j \geq c \tau(1 + \|\beta_0\|^2_2)$ and $\max_{j \leq p} \tilde{v}_j \leq C \tau(1 + \|\beta_0\|^2_2).$ Applying (B.4) in Lemma 8 given below with $\nu_{\min} = \min_{j \leq p} \tilde{v}_j$ and Corollary 1 with $q = 1$ we get

$$\|\hat{\beta}_T\|_0 \leq s + \frac{\|\beta_0\|_1}{c \tau(1 + \|\beta_0\|^2_2)} \leq s + \frac{C(1 + \|\beta_0\|^2_2) \sqrt{\log(pn)/(\alpha c)}}{c \tau(1 + \|\beta_0\|^2_2)} \leq C's$$

where we have used the fact that $\tau = n^{-1/2} \Phi^{-1}(1 - \alpha/(2pn)) \geq \sqrt{2 \log(2p/\alpha)}/n$.

Similarly, to prove the bounds on the $\ell_1$ and $\ell_2$ errors of the thresholded estimator, we use inequalities (B.3) and (B.5) in Lemma 8 below with $\nu_{\max} = \max_{j \leq p} \tilde{v}_j$, the bounds of Corollary 1 with $q \in \{1,2\}$, and the fact that $\tau \leq C \sqrt{\log(2p/\alpha)/n}$. \hfill \Box
The following lemma provides bounds for general thresholded estimators (see also a related lemma in [5]).

**Lemma 8.** Let $\hat{\beta}, \beta_0 \in \mathbb{R}^p$ be such that $\|\beta_0\|_0 \leq s$. Denote by $\hat{\beta}^\nu = (\hat{\beta}_1^\nu, \ldots, \hat{\beta}_p^\nu)$ the vector obtained by thresholding the components $\hat{\beta}_j$ of $\hat{\beta}$ as follows: $\hat{\beta}_j^\nu = \hat{\beta}_j 1\{\hat{\beta}_j \geq \nu_j\}$ where $\nu_j$ are positive numbers. Then,

\begin{align}
\|\hat{\beta}^\nu - \beta_0\|_1 & \leq \|\hat{\beta} - \beta_0\|_1 + sv_{\max}, \\
\|\hat{\beta}^\nu\|_0 & \leq s + \|\hat{\beta} - \beta_0\|_1/v_{\min}, \\
\|\hat{\beta}^\nu - \beta_0\|_2 & \leq \|\hat{\beta} - \beta_0\|_2 + 2\sqrt{s}v_{\max} + \frac{2\|\hat{\beta} - \beta_0\|_1}{\sqrt{s}}
\end{align}

where $v_{\max} = \max_{j \leq p} \nu_j$ and $v_{\min} = \min_{j \leq p} \nu_j$.

**Proof of Lemma 8.** Let $T = \text{supp}(\hat{\beta}_0)$. The bound (B.3) follows from the chain of inequalities

\[
\|\hat{\beta}^\nu - \beta_0\|_1 = \|((\hat{\beta}^\nu - \beta_0)_{T^c})\|_1 + \|((\hat{\beta}^\nu)(T^c))\|_1 \\
\leq \|((\hat{\beta}^\nu - \hat{\beta})_{T^c})\|_1 + \|((\hat{\beta} - \beta_0)_{T^c})\|_1 + \|((\hat{\beta}^\nu)_{T^c})\|_1 \\
\leq sv_{\max} + \|((\hat{\beta} - \beta_0)_{T^c})\|_1 + \|(\hat{\beta}^\nu)_{T^c}\|_1 \\
= sv_{\max} + \|\hat{\beta} - \beta_0\|_1.
\]

To prove the bound (B.4), set $\hat{T} = \text{supp}(\hat{\beta}^\nu)$, and note that

\[
\|\hat{\beta} - \beta_0\|_1 \geq \|\hat{\beta}_{T^c}\|_1 \geq \nu_{\min}\|\hat{T}^c \cap \hat{T}\| \geq \nu_{\min}\|\hat{T} - |T|\| \geq \nu_{\min}\|\hat{\beta}^\nu\|_0 - s.
\]

We now show (B.5). By the triangle inequality,

\[
\|\hat{\beta}^\nu - \beta_0\|_2 \leq \|\hat{\beta}^\nu - \hat{\beta}\|_2 + \|\hat{\beta} - \beta_0\|_2.
\]

Without loss of generality assume that the order of the components is such that $|\hat{\beta}_j^\nu - \beta_j|$ is non-increasing in $j$. Let $T_1$ be the set of indices $j$ corresponding to the $s$ largest values of $|\hat{\beta}_j^\nu - \beta_j|$. Similarly, define $T_k$ as the set of indices corresponding to the $s$ largest values of $|\hat{\beta}_j^\nu - \beta_j|$ outside $\cup_{m=1}^{k-1} T_m$. Therefore,

\[
\hat{\beta}^\nu - \hat{\beta} = \sum_{k=1}^{[p/s]} ((\hat{\beta}^\nu - \hat{\beta})_{T_k}).
\]

Moreover, $\|((\hat{\beta}^\nu - \hat{\beta})_{T_k})\|_2 \leq \|((\hat{\beta}^\nu - \hat{\beta})_{T_{k-1}})\|_1/\sqrt{s}$ in view of the monotonicity of the components. Thus,

\[
\|\hat{\beta}^\nu - \hat{\beta}\|_2 = \|\sum_{k=1}^{[p/s]} ((\hat{\beta}^\nu - \hat{\beta})_{T_k})\|_2 \\
\leq \|((\hat{\beta}^\nu - \hat{\beta})_{T_1})\|_2 + \sum_{k=2} \|((\hat{\beta}^\nu - \hat{\beta})_{T_k})\|_2 \\
\leq \|((\hat{\beta}^\nu - \hat{\beta})_{T_1})\|_2 + \sum_{k=2} \|((\hat{\beta}^\nu - \hat{\beta})_{T_k})\|_2 \\
\leq v_{\max}\sqrt{s} + \sum_{k=2} \|((\hat{\beta}^\nu - \hat{\beta})_{T_k})\|_1/\sqrt{s} \\
= v_{\max}\sqrt{s} + \|\hat{\beta}^\nu - \hat{\beta}\|_1/\sqrt{s} \\
\leq 2\sqrt{s}v_{\max} + 2\|\hat{\beta} - \beta_0\|_1/\sqrt{s}
\]

where we have used the bound $|\hat{\beta}_j^\nu - \beta_j| \leq \nu_j$ valid for all $j$, and then (B.3). Inequality (B.5) follows by combining the last display with (B.6).
C. Supplementary Material: Numerical and Optimizational Issues.

The pivotality of the self-normalized estimator is achieved by the introduction of \( p \) second order cone constraints which is more computationally demanding than the \( 2p \) linear constraints (associated with the near zero score condition). In order to solve the optimization problem defined in (2.2), it is convenient to formulate it as

\[
\min_{\theta, \nu} \ c^T \theta \\
\text{s.t. } A\theta + \nu = b \\
(\theta, \nu) \in \mathbb{R}^d \times \mathcal{K},
\]

where \( \theta \) is a vector that contains the positive and negative parts of \( \beta \) and auxiliary variables, and \( \mathcal{K} \) is the cartesian product of non-negative cones and second order cones. The introduction of residual variables \( \varepsilon_i = y_i - z_i^T (\beta^+ - \beta^-) \) proves to be helpful in the implementation to further exploit sparsity in the design matrix in the \( p \) second order constraints. Indeed the additional residual variables allow us to write the second order constraints for \( j = 1, \ldots, p \) as

\[
\left\{ \frac{1}{n} \sum_{i=1}^{n} \left\{ z_{ij} \varepsilon_i + \hat{\Gamma}_{jj} (\beta^+_j - \beta^-_j) \right\}^2 \right\}^{1/2} \leq t_j
\]

instead of

\[
\left\{ \frac{1}{n} \sum_{i=1}^{n} \left\{ z_{ij} (y_i - z_i^T (\beta^+ - \beta^-)) + \hat{\Gamma}_{jj} (\beta^+_j - \beta^-_j) \right\}^2 \right\}^{1/2} \leq t_j.
\]

The difference in these representations come from what multiplies \( \beta^+ - \beta^- \). In the first formulation, \( \text{diag}(z_{1j}, z_{2j}, \ldots, z_{pj}) \) multiplies \( \varepsilon \) while \( e \Gamma_j \) multiplies \( \beta^+ - \beta^- \). In the second formulation we have \( -z_{ij} z_i^T + e \Gamma_j \) multiplying \( \beta^+ - \beta^- \) where \( e \) is the \( n \)-vector of ones. These three matrices have \( n \) rows but they are sparse in the first formulation and typically dense in the second formulation. Since these matrices are formed \( p \) times (one for each \( j \)), this has non-negligible consequences on the software performance.

D. Supplementary Material: Additional Simulations.

In this section, we provide additional simulations to illustrate the finite sample performance of the self-normalized conic estimator and its thresholded version. We consider both the additive errors in variables (EIV) and the covariates missing at random. The latter is a setting where the bias correction matrix is estimated from the data, while for the additive EIV setting we assume for simplicity that this matrix is known.
Case 1 - Additive EIV: consider the data generating process where $\xi_i$, $w_i$, and $x_i$ are independent and Gaussian. More precisely we set $\xi_i \sim N(0, \sigma^2_\xi)$, $w_i \sim N(0, \sigma^2_w I_{p \times p})$, and $x_i \sim N(0, \Sigma)$ where $I_{p \times p}$ is an identity matrix and $\Sigma$ is a $p \times p$ matrix with elements $\Sigma_{ij} = \rho_{|i-j|}$. We set $\sigma_\xi = 1$, $\sigma_w = 1$ and $\rho = 0.5$. We assume $\sigma_w$ to be known in all calculations so we set $\hat{\Gamma} = \sigma_w^2 I_{p \times p}$ so that $b_0 = 0$.

Case 2 - Covariates missing at random: here we consider the case where the error in measurements represents missing data. For this purpose we follow the framework of [26], i.e., we observe $(y_i, \tilde{z}_i, \eta_i, i = 1, \ldots, n)$ where

$$\tilde{z}_{ij} = x_{ij}\eta_{ij}, \quad \eta_{ij} \text{i.i.d Bernoulli with parameter } 1 - \pi,$$

the r.v.’s $\xi_i$, and $x_i$ are generated as for Case 1 and $\eta_{ij} = 0$ indicates that we are missing the observation $x_{ij}$. For numerical comparisons, the parameter $\pi$ is chosen uniformly from the interval $(0, 1, 0.75)$ for each simulated repetition. The bias correction matrix is estimated as described in [26] and we set $b_e = c\sqrt{\log(2p/\epsilon)/n}$, $c = 0.25$, $\epsilon = 0.05$.

We consider two types of coefficients $\beta_0$: (i) $\beta_0 = (1, \ldots, 1, 0, \ldots, 0)$ where the first six coefficients are set to one, (ii) $\beta_0 = (1, \frac{1}{2}, \frac{1}{2}, \frac{1}{2}, \frac{1}{2}, 0, \ldots, 0)$. The first vector of coefficients illustrates the case where parameters are well separated from zero, and the second case is without such a separation. The latter typically leads to model selection mistakes with high probability.

The estimators proposed in this paper, namely the self-normalized estimator (SN-conic) and its thresholded version (SN-conic thresholded) are compared with the conic estimator (Conic) proposed in [1]. We also consider the refitted estimator (SN-conic refitted) defined as follows: We first find the selected set of variables for the thresholded SN-conic estimator and then compute the SN-conic estimator for the model restricted to this set. We provide additional benchmarks for the performance, namely the biased and the no measurement error Lasso and Dantzig selector respectively. The biased versions are obtained with the observed design variables $z_i$’s and the no measurement error versions are computed with the unobserved design variables $x_i$’s. We report the following metrics which are computed based on 100 simulated repetitions: bias ($\|E[\hat{\beta} - \beta_0]\|_2$), root mean squared error (RMSE, $E[\|\hat{\beta} - \beta_0\|^2]^{1/2}$), prediction bias (PRb, $E[\|X(\hat{\beta} - \beta_0)\|]_2/\sqrt{n}$), $\ell_2$-rate (L2, $E[\|\hat{\beta} - \beta_0\|^2]$), $\ell_1$-rate (L1, $E[\|\hat{\beta} - \beta_0\|_1]$), prediction risk (PR, $E[\|X(\hat{\beta} - \beta_0)\|]/\sqrt{n}$), false positives (FP, expected number of misidentified zero elements of $\beta_0$), false negatives (FN, expected number of misidentified non-zero elements of $\beta_0$), and time (average computation time in seconds (CPU: i7@3.1GHz, 16GB RAM)).

The conic estimator is tuned assuming that $\sigma_\xi = 1$ is known and setting $\tau = \sqrt{\log(p/\alpha)/n}$ while the SN-conic has its penalty parameters set to $\tau = cn^{-1/2}\Phi^{-1}(1 - \alpha/2p)$, $c = 1, 0.5$, $\alpha = 0.05$ and $\lambda_t = 1$, $\lambda_u = 0.25$. Similarly to the conic estimator, Lasso and Dantzig selector are also tuned assuming that $\sigma_\xi = 1$ and we set their regularization parameters to $2cn^{-1/2}\Phi^{-1}(1 - \alpha/(2p))$ where
\[ c = 1.1, \alpha = 0.05 \text{ (as suggested in [3]), and } \sqrt{2(\log p)/n}, \text{ respectively. Computations are performed in R using the optimization software Mosek, an interior point methods solver, wrapped through the R package Rmosek. The Dantzig selector is computed via the R package quantreg [21]. }

The proposed methods, SN-conic, SN-conic thresholded and SN-conic refitted provide good results at all three levels of \( p \) considered in the simulations, with the performance deteriorating slightly with increase in dimension. The results for the additive error case are reported in Tables 2 to 5 and the results for the missing covariates case are reported in Tables 6 to 9. These numerical findings support our theoretical results regarding consistency of the proposed methods. The poor performance of biased Lasso and Dantzig selector highlights the impact of disregarding errors in variables. The self-normalized estimators at \( c = 1/2 \) outperform the Conic estimator in all designs considered. At \( c = 1 \) the SN-conic refitted estimator outperforms the Conic estimator at higher dimensions (\( p = 100 \) and \( p = 400 \)) and they are competitive at \( p = 10 \). We note that the (non self-tuning) Conic estimator provides a slightly better efficiency in comparison to SN-conic and SN-conic thresholded at \( c = 1 \).

Among the self-normalized estimators proposed here, the main difference between SN-conic thresholded and SN conic is in the significantly reduced number of false positives in the thresholded version. This comes at a price of a slightly higher false negative rate especially in the case where the coefficients are not well separated from zero, see Tables 4, 5, 8, 9. Another expected outcome is the reduction in bias obtained via the refitted version. Lastly, in context of computation time it may be of interest to note that it is an average of computation times over 100 replications running parallel on 8 cores and is thus subject to additional computational overhead time per instance, induced by the parallel processing. The computation times for running a dedicated single instance for all of the estimators are three to five times faster.

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### Table 2

Additive error: numerical comparisons with separated coefficients at $n = 300$

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<tr>
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<tr>
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<tr>
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<tr>
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</table>
\textbf{Table 3}

Additive error: numerical comparisons with separated coefficients at $n = 400$

| $n = 400$ | $\beta = (1,1,1,1,1,0,...,0)$ | \multicolumn{8}{c|}{\textbf{Time}} |
|-----------|-----------------------------|-----------------|----------------|----------------|----------------|----------------|----------------|----------------|----------------|
|           | $p$ | Bias | RMSE | PRb | L2 | L1 | PR | FP | FN |  |
| SN-conic ($c = 1$) | 10 | 0.596 | 0.815 | 0.092 | 0.794 | 1.621 | 0.889 | 0.590 | 0.000 | 0.959 |
|           | 100 | 0.774 | 0.919 | 0.107 | 0.907 | 1.888 | 1.113 | 12.050 | 0.000 | 40.442 |
|           | 400 | 0.882 | 1.042 | 0.122 | 1.027 | 2.131 | 1.272 | 387.790 | 0.000 | 48.223 |
| SN-conic ($c = 1$) (thresholded) | 10 | 0.597 | 0.817 | 0.092 | 0.795 | 1.619 | 0.890 | 0.040 | 0.030 | 0.959 |
|           | 100 | 0.775 | 0.920 | 0.108 | 0.908 | 1.889 | 1.114 | 0.020 | 0.020 | 40.442 |
|           | 400 | 0.892 | 1.060 | 0.124 | 1.042 | 2.148 | 1.287 | 387.790 | 0.000 | 48.223 |
| SN-conic ($c = \frac{1}{2}$) | 10 | 0.316 | 0.640 | 0.059 | 0.612 | 1.286 | 0.563 | 1.400 | 0.000 | 0.971 |
|           | 100 | 0.395 | 0.659 | 0.064 | 0.634 | 1.425 | 0.640 | 1.290 | 0.000 | 42.147 |
|           | 400 | 0.450 | 0.712 | 0.071 | 0.692 | 1.542 | 0.714 | 387.790 | 0.000 | 58.474 |
| SN-conic ($c = \frac{1}{2}$) (thresholded) | 10 | 0.316 | 0.640 | 0.059 | 0.612 | 1.286 | 0.563 | 0.420 | 0.000 | 0.971 |
|           | 100 | 0.395 | 0.659 | 0.064 | 0.634 | 1.425 | 0.640 | 1.290 | 0.000 | 42.147 |
|           | 400 | 0.449 | 0.707 | 0.071 | 0.692 | 1.542 | 0.714 | 387.790 | 0.000 | 58.474 |
| SN-conic ($c = 1$) (refitted) | 10 | 0.553 | 0.786 | 0.087 | 0.763 | 1.549 | 0.837 | 0.040 | 0.030 | 1.749 |
|           | 100 | 0.551 | 0.743 | 0.081 | 0.723 | 1.480 | 0.819 | 0.020 | 0.020 | 40.861 |
|           | 400 | 0.567 | 0.840 | 0.085 | 0.798 | 1.583 | 0.870 | 0.000 | 0.250 | 53.888 |
| SN-conic ($c = \frac{1}{2}$) (refitted) | 10 | 0.295 | 0.633 | 0.058 | 0.606 | 1.268 | 0.548 | 0.360 | 0.030 | 1.687 |
|           | 100 | 0.286 | 0.624 | 0.056 | 0.599 | 1.342 | 0.559 | 1.160 | 0.000 | 41.852 |
|           | 400 | 0.263 | 0.662 | 0.059 | 0.637 | 1.460 | 0.594 | 1.560 | 0.000 | 59.883 |
| Conic (no meas error) | 10 | 0.492 | 0.827 | 0.081 | 0.791 | 1.631 | 0.783 | 0.370 | 0.020 | 0.149 |
|           | 100 | 0.508 | 0.829 | 0.085 | 0.804 | 1.691 | 0.859 | 0.420 | 0.020 | 0.428 |
|           | 400 | 0.607 | 0.878 | 0.090 | 0.850 | 1.782 | 0.925 | 0.530 | 0.000 | 1.662 |
| Lasso (biased) | 10 | 0.893 | 0.923 | 0.131 | 0.921 | 2.299 | 1.290 | 3.940 | 0.000 | 0.082 |
|           | 100 | 0.929 | 0.981 | 0.130 | 0.979 | 3.068 | 1.336 | 54.810 | 0.000 | 0.510 |
|           | 400 | 0.950 | 1.036 | 0.128 | 1.054 | 4.285 | 1.348 | 106.330 | 0.000 | 1.308 |
| Lasso (no meas error) | 10 | 0.188 | 0.240 | 0.029 | 0.235 | 0.486 | 0.279 | 3.220 | 0.000 | 0.076 |
|           | 100 | 0.226 | 0.282 | 0.033 | 0.277 | 0.572 | 0.332 | 0.310 | 0.000 | 0.400 |
|           | 400 | 0.241 | 0.290 | 0.033 | 0.287 | 0.608 | 0.359 | 0.090 | 0.000 | 1.226 |
| Dantzig selector (biased) | 10 | 0.798 | 0.841 | 0.115 | 0.838 | 2.230 | 1.132 | 3.870 | 0.000 | 0.013 |
|           | 100 | 0.814 | 1.222 | 0.131 | 1.220 | 8.684 | 1.263 | 89.340 | 0.000 | 0.186 |
|           | 400 | 0.843 | 2.595 | 0.180 | 2.590 | 36.911 | 1.971 | 331.630 | 0.000 | 15.756 |
| Dantzig selector (no meas error) | 10 | 0.022 | 0.175 | 0.014 | 0.169 | 0.421 | 0.137 | 3.340 | 0.000 | 0.007 |
|           | 100 | 0.050 | 0.547 | 0.042 | 0.545 | 3.850 | 0.422 | 74.870 | 0.000 | 0.165 |
|           | 400 | 0.103 | 0.994 | 0.073 | 0.992 | 12.375 | 0.753 | 251.020 | 0.000 | 13.172 |
Additive error: numerical comparisons with unseparated coefficients at $n = 300$

<table>
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<tr>
<th>Method</th>
<th>p</th>
<th>Bias</th>
<th>RMSE</th>
<th>PR</th>
<th>L2</th>
<th>L1</th>
<th>PRb</th>
<th>L2</th>
<th>L1</th>
<th>PR</th>
<th>FP</th>
<th>FN</th>
<th>Time</th>
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<td>0.754</td>
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<td>SN-conic ($c = \frac{1}{2}$) (refitted)</td>
<td>10</td>
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<td>0.376</td>
<td>0.036</td>
<td>0.362</td>
<td>0.767</td>
<td>0.336</td>
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<td>0.039</td>
<td>0.403</td>
<td>0.899</td>
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<td>34.446</td>
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<td>0.464</td>
<td>0.041</td>
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<td>0.42</td>
<td>1.77</td>
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<td>0.453</td>
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<td>0.06</td>
<td>0.515</td>
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<td>1.99</td>
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</tr>
<tr>
<td>Lasso (biased)</td>
<td>10</td>
<td>0.577</td>
<td>0.597</td>
<td>0.076</td>
<td>0.594</td>
<td>1.08</td>
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<td>0.049</td>
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<td>0.626</td>
<td>0.076</td>
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<td>1.241</td>
<td>0.776</td>
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</tr>
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<td>0.653</td>
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<td>0.68</td>
<td>0.696</td>
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<td>0.298</td>
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<td>0.045</td>
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<td>0.519</td>
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<td>0.588</td>
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<td>0.721</td>
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<td>1.274</td>
<td>15.041</td>
<td>1.027</td>
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<td>0.29</td>
<td>11.757</td>
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</tr>
<tr>
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<td>0.538</td>
<td>0.168</td>
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<td>0.179</td>
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<td>0.082</td>
<td>0.958</td>
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<td>11.037</td>
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</tr>
</tbody>
</table>

Table 4

Additive error: numerical comparisons with unseparated coefficients at $n = 300$
\[
\beta = (1, 1/2, 1/3, 1/4, 1/5, 1/10, 0, \ldots, 0)
\]

<table>
<thead>
<tr>
<th>n = 400</th>
<th>p</th>
<th>Bias</th>
<th>RMSE</th>
<th>PRb</th>
<th>L2</th>
<th>L1</th>
<th>PR</th>
<th>FP</th>
<th>FN</th>
<th>Time</th>
</tr>
</thead>
<tbody>
<tr>
<td>SN-conic (c = 1)</td>
<td>10</td>
<td>0.338</td>
<td>0.418</td>
<td>0.05</td>
<td>0.41</td>
<td>0.859</td>
<td>0.501</td>
<td>0.11</td>
<td>1.17</td>
<td>0.988</td>
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<td>100</td>
<td>0.419</td>
<td>0.478</td>
<td>0.061</td>
<td>0.473</td>
<td>1.001</td>
<td>0.615</td>
<td>3.01</td>
<td>0.99</td>
<td>40.715</td>
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<td>0.688</td>
<td>384.6</td>
<td>0</td>
<td>49.009</td>
</tr>
<tr>
<td>SN-conic (c = 1) (thresholded)</td>
<td>10</td>
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<td>0.425</td>
<td>0.051</td>
<td>0.418</td>
<td>0.874</td>
<td>0.512</td>
<td>0</td>
<td>2.06</td>
<td>0.988</td>
</tr>
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<td>0.484</td>
<td>1.027</td>
<td>0.632</td>
<td>0</td>
<td>2.63</td>
<td>40.715</td>
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<td>0.544</td>
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<td>0.538</td>
<td>1.143</td>
<td>0.713</td>
<td>0</td>
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<td>49.009</td>
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<td>10</td>
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<td>0.336</td>
<td>0.034</td>
<td>0.322</td>
<td>0.687</td>
<td>0.323</td>
<td>0.18</td>
<td>1.17</td>
<td>1.032</td>
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<td>0.039</td>
<td>0.349</td>
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<td>0.361</td>
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<td>1.32</td>
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<td>0.401</td>
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<td>1.47</td>
<td>61.968</td>
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<td>0.329</td>
<td>0.033</td>
<td>0.318</td>
<td>0.671</td>
<td>0.31</td>
<td>0.15</td>
<td>1.17</td>
<td>1.676</td>
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<td>0.35</td>
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<td>0.42</td>
<td>0.04</td>
<td>0.409</td>
<td>0.955</td>
<td>0.38</td>
<td>1.33</td>
<td>1.51</td>
<td>63.879</td>
</tr>
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<td>0.04</td>
<td>0.381</td>
<td>0.807</td>
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<td>0.418</td>
<td>0.051</td>
<td>0.411</td>
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<td>1.52</td>
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<td>0.442</td>
<td>0.921</td>
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<tr>
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<td>0.577</td>
<td>0.589</td>
<td>0.07</td>
<td>0.587</td>
<td>1.072</td>
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<td>0.23</td>
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<td>0.626</td>
<td>0.079</td>
<td>0.624</td>
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<td>0.772</td>
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<td>0.45</td>
<td>1.357</td>
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<td>0.027</td>
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<td>0.514</td>
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<td>0.594</td>
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<td>308.59</td>
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<td>0.183</td>
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<td>0.177</td>
<td>0.442</td>
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<td>3.55</td>
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<td>0.01</td>
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</table>

Table 5
Additive error: numerical comparisons with unseparated coefficients at n = 400
\[ \beta = (1, 1, 1, 1, 1, 0, \ldots, 0) \]

**Table 6**

*Missing covariates: numerical comparisons with separated coefficients at \( n = 300 \*)

<table>
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<tr>
<th>( n = 300 )</th>
<th>( p )</th>
<th>Bias</th>
<th>RMSE</th>
<th>PRb</th>
<th>L2</th>
<th>L1</th>
<th>PR</th>
<th>FP</th>
<th>FN</th>
<th>Time</th>
</tr>
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<tbody>
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<td><strong>SN-conic (c = 1)</strong></td>
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<td>0.715</td>
<td>1.478</td>
<td>0.73</td>
<td>1.88</td>
<td>0.29</td>
<td>0.795</td>
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<td>0.176</td>
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<td>2.632</td>
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<td>0.06</td>
<td>0.85</td>
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<td>0.18</td>
<td>1.258</td>
<td>2.723</td>
<td>1.651</td>
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<td>0.82</td>
<td>56.727</td>
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<tr>
<td><strong>SN-conic (c = 1/2)</strong></td>
<td>10</td>
<td>0.466</td>
<td>0.779</td>
<td>0.081</td>
<td>0.716</td>
<td>1.472</td>
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<td>0.772</td>
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<td>0.593</td>
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<td>0.803</td>
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<td>0.1</td>
<td>17.801</td>
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<td>0.781</td>
<td>0.081</td>
<td>0.716</td>
<td>1.472</td>
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 & & \text{p} & \text{Bias} & \text{RMSE} & \text{PRb} & \text{L2} & \text{L1} & \text{PR} & \text{FP} & \text{FN} & \text{Time}
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\text{SN-conic (c = 1)} & 10 & 0.051 & 0.871 & 0.107 & 0.814 & 1.699 & 0.963 & 1.24 & 0.02 & 0.852
\hline
\text{SN-conic (c = 1) (thresholded)} & 10 & 0.052 & 0.874 & 0.107 & 0.816 & 1.695 & 0.966 & 0.1 & 0.08 & 0.852
\hline
\text{SN-conic (c = 1) (thresholded)} & 10 & 0.387 & 0.646 & 0.068 & 0.595 & 1.237 & 0.605 & 2 & 0 & 0.841
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\text{SN-conic (c = 1/2) (thresholded)} & 10 & 0.369 & 0.637 & 0.066 & 0.584 & 1.205 & 0.583 & 0.4 & 0.03 & 0.841
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\text{SN-conic (c = 1/2) (refitted)} & 10 & 0.512 & 0.852 & 0.085 & 0.797 & 1.652 & 0.807 & 0.61 & 0.04 & 0.138
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\text{Conic (no meas error)} & 10 & 0.018 & 0.918 & 0.133 & 0.854 & 2.111 & 1.189 & 3.86 & 0 & 0.098
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\text{Lasso (biased)} & 10 & 0.186 & 0.246 & 0.028 & 0.24 & 0.492 & 0.279 & 3.16 & 0 & 0.047
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\text{Lasso (no meas error)} & 10 & 0.225 & 0.285 & 0.032 & 0.281 & 0.582 & 0.335 & 0.2 & 0 & 0.48
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\text{Dantzig selector (biased)} & 10 & 0.714 & 0.847 & 0.12 & 0.772 & 2.048 & 1.028 & 3.79 & 0 & 0.009
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\caption{Missing covariates: numerical comparisons with separated coefficients at \(n = 400\)}
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| Table 8 |

Missing covariates: numerical comparisons with unseparated coefficients at $n = 300$
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Table 9
Missing covariates: numerical comparisons with unseparated coefficients at $n = 400$